

OUCT Polaris is actively involved in open source activities and has made presentations at ROSCONJP, a ROS conference.

They have also presented their results at the Robotics Society of Japan and other conferences.

<https://roscon.jp/presentations/06.pdf>

<https://vimeo.com/showcase/11452054/video/1029114585>

[https://www.rsj.or.jp/content/files/event/openforum/2022/OF3/RSJ2022\\_OF3\\_1\\_Mizoguchi.pdf](https://www.rsj.or.jp/content/files/event/openforum/2022/OF3/RSJ2022_OF3_1_Mizoguchi.pdf)

<https://konorobo.main.jp/konorobo2022/speakers2022/ouxt-polaris/>