

RoboSub 2026 | Team Handbook

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Welcome to the frontlines of innovation at the 2026 RoboSub Competition!

This Team Handbook contains information that teams need to compete at the 2026 RoboSub Competition. It includes task descriptions, rules, and requirements, and other guidance and specifications. Teams are encouraged to read this document for a thorough understanding of what is necessary to compete effectively.

Why compete in RoboSub?

RoboSub is an international student program established to generate, cultivate, and enhance a community of innovators by challenging new generations of engineers capable of making substantive contributions to the autonomous underwater vehicle (AUV) domain. Student teams tackle fundamental challenges in the design of ocean systems, while getting hands-on experience by designing, building and testing a fully autonomous vehicle. By providing a venue and mechanism to share knowledge and innovate, students are primed for jobs in developing, documenting, testing and managing state-of-the-art systems.

The nominal winners are those teams that have scored the most points. The real winners are all those participants who have learned something lasting about working together to create an autonomous system that accomplished a challenging mission in a complex environment.

Why robotics competitions?

The goals of the RoboNation student competitions are to provide opportunities for students to experience the challenges of systems engineering, to develop skills in accomplishing realistic missions with autonomous vehicles, and to foster relationships between young engineers and the organizations developing and producing autonomous vehicle technologies. The objective is to produce the people who will push the envelope in the future. Competitors gain an appreciation for the tradeoffs inherent in any system design and the lessons learned in transitioning from a working bench prototype to operating reliably in the real world.

Maritime autonomous technology is critical to monitoring and healing our oceans. Developing human resources to expand this effort is even more essential.

RoboSub Organizers

The RoboSub Program is brought to you by RoboNation, Inc. and the U.S. Office of Naval Research.



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Change Log

Date	Section	Details
2026-03-07		First Release
2026-04-16	Section 3.2.5	Updated the units for far (1 ft) and farther (1.5 ft)
2026-05-21	Section 3.4 Section 4.2	• Added course layout • Clarified time bonus
2026-06-08	Section 3.2	• Added images for each tasks
2026-06-11	Section 4.2 Build Guide ↗ : Underwater Magnetically Activated Light	• Published Autonomy Challenge scoring breakdown • Released new section with build guide for magnetic light used in Task 3.

What's New for 2026

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Capability Levels

Each mission task has capabilities divided by three levels:

- ***Core Capabilities:*** Fundamental competencies required for safe and effective baseline autonomous operation.
- ***Advanced Capabilities:*** Competencies that reflect growth in autonomy sophistication and real-world relevance.
- ***Disruptive Capabilities:*** Transformative competencies pushing the boundary of autonomous systems - enabling novel or mission-critical applications.

Section 1: Competition Overview

1.1 Dates & Venue

The 2026 RoboSub Competition (RoboSub 2026) will be held 11-16 July 2026 at the Woollett Aquatics Center in Irvine, California, USA.

1.2 Competition Structure

RoboSub includes (1) the [Design Documentation](#) that presents each team's work and system design; and (2) [Autonomy Challenge](#) that demonstrates an AUV's autonomous performance and safety.

1.3 Competition Theme: Storm Response

Technology in Action for Recovery and Relief. *Storm Response* explores the power uncrewed systems play in recovery, resilience, and discovery in disaster relief efforts. Framed as an opportunity, not just to restore what was lost, but to rebuild smarter and reimagine the future; this season's challenges reflect the real-world role of robotics in helping communities respond to and recover from storms and other natural events. Through hands-on missions grounded in post-disaster scenarios, teams will apply technology with purpose – restoring harbor operations, assessing underwater infrastructure, supporting exploration, and unlocking new possibilities.

Find out more in [Section 3: Autonomy Challenge](#) ↗ for the tasks.

1.4 Eligibility

Student teams from anywhere in the world are eligible to participate. All teams must build an AUV to compete and may enter one or two vehicles in the competition. *

**First-year teams are eligible to participate in RoboSub without an AUV. These teams are expected to participate in Design Documentation and send representatives on-site at the event as a learning experience. First-year teams are expected to indicate this option in their registration form.*

1.4.1 Eligibility Details & Team Composition

- Teams must be comprised of 75% or more full-time students. Student members are expected to make significant contributions to the engineering development cycle of their AUV.
 - The majority of team members must be college or high school students. Teams may also include middle school students. Interdisciplinary teams are encouraged.
 - Teams may be comprised of 25% or less, mentors or advisors, alumni, industry, academic or government partners.
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1.5 Competition Schedule and Timeline

The event schedule is also available on the [RoboSub website](#) ↗.

Date	Event	Location
Online Registration & Submissions		
01 December 2025 - 01 April 2026	Registration	Registration Portal ↗ (Online)
27 May 2026	Event Submission Deadline: • Team Member Registration • Team Demographics • Merchandise Order • Vehicle Information • On-Site Requirements Design Documentation Deadline: • Technical Design Report • Website • Team Introduction Video • Communicaty & Outreach (optional)	Registration Portal ↗ (Online)
24 June 2026	Pre-Qualification Maneuver	Pre-Qualification Form ↗ (Online)
In-Person Event		
11 July (early afternoon)	Team Check-in / Orientation	Woollett Aquatics Center
12-13 July	Practice Course Open Qualifying Round Design Presentations System Assessments	Woollett Aquatics Center
14-15 July	Semi-Finals Round	Woollett Aquatics Center
16 July	Finals Round Awards	Woollett Aquatics Center

1.6 Points of Contact

RoboSub Questions:	Registration Questions:	On-Site Logistics/Safety:
robosub.org/discord ↗ competitions@robonation.org ✉	support@robonation.org ✉	events@robonation.org ✉ 850.642.053

1.7 RoboNation Code of Conduct

All team members must abide by the RoboNation Code of Conduct while participating in the Competition. Failure to abide by this Code of Conduct at any point during the competition season may result in the disqualification of the team and/or participants from the Competition, and/or disqualification from components of the competition, the full competition, and/or future competitions.

1. Give your best effort. Display honesty, integrity, and sportsmanship while engaging in friendly competition. Compete fairly. Team products are solely the creation of student participants' own efforts, ideas, and designs with supporting mentors providing only verbal advice.
2. Respect others. All participants and guests will display courtesy and respect toward officials, volunteers, other teams, and guests of the Competition.
3. Act with integrity. All participants and guests will behave in a responsible manner and follow the rules of the competition and host organization.
4. Support each other. All participants will embody the spirit of RoboNation and endeavor to engage with, learn from, and support one another.

Section 2: Design Documentation

Delivered Online Before On-Site Competition

The following design documentation are delivered online prior to the on-site competition according to the deadlines found in [1.5 Competition Schedule](#). Teams are encouraged to refer to the past top-scored deliverables: robosub.org/past-programs ↗.

- [2.1 Technical Design Report](#)
- [2.2 Team Website](#)
- [2.3 Team Introduction Video](#)

Delivered On-Site during Competition

The following design documentation are delivered on-site during the competition.

- [2.4 Design Strategy Presentation](#)
- [2.5 System Assessment](#)

2.1 Technical Design Report

Each team is required to submit a Technical Design Report (TDR) in English (US) that describes the team's design principles and competition priorities. The report should address the rationale for which autonomy challenge tasks have been chosen for the team to attempt and how this competition strategy influenced the design decisions for the hull, propulsion system, control systems, and autonomy system. Teams must follow the TDR instructions provided in this section. To be eligible for full points, teams must submit their TDR by the deadline found in [Section 1.5](#).

A strong TDR provides a coherent narrative and addresses the elements of the rubric as much as possible, including citations of the references used. The competition strategy justifies the choices of autonomy challenge tasks and systems design decisions that trace back to those task choices. The report also identifies which software tools allow the team to accomplish the tasks chosen.

✓ **Top-Scored Report:** Get inspiration from National University of Singapore's first place report from RoboSub 2025. View the [report here](#) ↗.

The technical design report is worth a maximum total of **200 points**. The outline of each content section includes a scoring weight with guidance for scoring considerations that are provided to the judges during evaluations.

2.1.1 Deliverable Requirements

The content of the written paper shall include the following sections:

- [Abstract](#)
- [Acknowledgements](#)
- [References](#)
- Technical Content: [Competition Strategy](#), [Design Strategy](#), [Testing Strategy](#)
- [Optional Appendix: Test Plan & Results](#)

The format of the written paper shall adhere to the following guidelines:

- 6 page limit (excluding Cover Page, References and Appendices)
- 8.5 × 11 in. page size
- Margins ≥ 0.8 in.

- Font: Times New Roman 12pt
- Header on every page including team name and page number
- Submitted in .pdf format

Optional Formatting: Teams may choose to follow the two-column format, editorial style for IEEE Conference Proceedings: www.ieee.org/conferences/publishing/templates.html ↗.

RoboNation Tip: It is recommended that papers be peer-reviewed prior to submission. For example, teams can utilize resources at their institution, fellow students, or professional editing services.

Formatting Scoring Metrics (5% of score)

Strong	Paper follows page limit, and all formatting guidelines are followed. The document is professionally organized. All required sections are included and easy to identify. All grammar, punctuation, and spelling are correct. The style follows that expected of a scientific paper submitted for publication.
Requirements Not Met	Formatting guidelines are not followed and the layout is unorganized.

2.1.2 Abstract

The abstract is a short summary of the main points in the paper. The abstract should summarize the linkage between overall competition strategy and system architecture, design, and engineering decisions.

RoboNation Tip: Find out more about how to best write an abstract [here](#) ↗. ([University of Wisconsin–Madison: The Writing Center](#) ↗)

Abstract Scoring Metrics (10% of score)

Outstanding	Abstract is engaging, lists the scope of the work, and provides a thorough summary of the paper.
Strong	Abstract provides a strong overview of the scope of work and a detailed summary of the paper.
Average	An adequate explanation of the scope of work is included with a brief summary of the paper.
Below Average	Abstract provides a basic summary of the paper.
Poor	Abstract section is included but does not serve the intent of an abstract. The abstract is treated as an introduction and provides no summary of the paper.
Requirements Not Met	No abstract is included.

2.1.3 Acknowledgements

Participating in the competition, as in all research projects, involves leveraging resources and support beyond the efforts of individual team members. This support can take many forms such as technical advice, labor, equipment, facilities, and monetary contributions. Acknowledging those who have supported efforts is important.

Acknowledgements Scoring Metrics (5% of score)

Strong	Acknowledgements detail supporting personnel and their contributions as well as resources. Sponsors and their contributions are acknowledged.
Average	Acknowledgements include a list of supporters and sponsors with little or no detail of the support provided.
Poor	Acknowledgements provide a general thank you but do not specify particular contributions.
Requirements Not Met	No acknowledgements are included.

2.1.4 References

As with any technical publication, original ideas and content not generated by the paper's authors should be properly cited. The references should follow the [IEEE Conference Proceedings citation style](#) ⁷.

References Scoring Metrics (5% of score)

Strong	Sources include notable technical references including technical papers and articles. Use of the source materials are evident in the TDR. Sources are thoroughly documented. The IEEE citation style is correctly utilized.
Average	Sources are adequate and documented correctly with the IEEE citation style is utilized.
Poor	Limited sources are documented but there is no adherence to the IEEE citation style.
Requirements Not Met	No sources or citations are documented.

2.1.5 Competition Strategy

The paper must include details on the team's strategy for the competition, including the plans for approaching the course and how the vehicle design relates to this approach. The course consists of multiple tasks with associated points for accomplished behaviors. The only required task is navigating through the start gates. Teams may choose to attempt the other tasks and complete the tasks in any order. The more tasks a vehicle is designed and engineered to accomplish, the more complex the overall vehicle system will be.

Discuss the team's strategy on trade-offs between system complexity and reliability. For example, teams have a limited number of working hours to prepare for the competition; this time could be spent adding additional capabilities or testing and improving the reliability of an existing capability. As system complexity grows, changes in subsystems can propagate in unmanageable ways when time is limited. Based on history and the systems engineering talents of the team, include a description the team's strategic vision.

Competition Strategy Scoring Metrics (25% of score)

Outstanding	Detailed description of the team's strategic vision and how the vehicle design compliments their goals. Detailed discussion on trade-off studies between system complexity and reliability during design development process.
Strong	The team's goals are clearly evident but not discussed in detail. Trade-off studies evident but lacking details.
Average	Brief mention of team's strategic goals and/or trade-off studies.
Below Average	Document hints at a goal for competition and/or trade-off studies.
Poor	Discussion of the team's vision is incoherent; rationale for competition goals is not discussed.
Requirements Not Met	No mention of competition goals.

2.1.6 Design Strategy

Given the strategy for success at the competition and the approach to managing complexity, the paper must include a description of the systems design to meet the goals they established for the competition. Justification for design choices should be clear. Discuss how components and subsystems were selected and integrated on the vehicle. For teams that are working with a previously designed vehicle, discuss how the design meets the current competition strategy and any modifications needed at the component, subsystem, and/or integrated systems levels. Describe the experience in making both architectural/design decisions and systems engineering decisions.

This section should not include detailed component descriptions and/or specifications not of original design. Instead, it should focus on WHY design decisions were made and HOW they were influenced by competition requirements.

Design Strategy Scoring Metrics (25% of score)

Outstanding	Provides in-depth explanations on design strategy and clearly identifies creative aspects of system. Creative design methodology is justified with required calculation steps and visual aids. Content clearly exhibits a Systems Engineering approach.
Strong	Provides explanations on design strategy and identifies creative aspects of system. Creative design methodology is justified with calculation steps and visual aids. Content hints at a Systems Engineering approach.
Average	Provides some information on design strategy and creative aspects of system. Creative design methodology is supported with a few calculations. Content could be justified as a Systems Engineering approach.
Below Average	Provides little information on design and creative design methodology. Little evidence to support applications of a Systems Engineering approach.
Poor	Provides limited information on the creative aspects of system. Creative design methodology is hypothesized. No evidence to support application of Systems Engineering principles.
Requirements Not Met	Creative aspects of design are not described.

2.1.7 Testing Strategy

Testing and experimentation is a crucial step to preparing and innovating a systems design that strongly correlates with a competitive performance in the arena. The paper must include the approach to a testing strategy, including various test plans, both physically and in simulation.

Discuss considerations of the time needed to thoroughly test to meet the determined goals and the demands of design and engineering with those of testing and experimentation.

Testing Strategy Scoring Metrics (25% of score)

Outstanding	Testing approach is presented in great detail, to include test strategy and plans. Component testing, sensor and control systems testing done in accordance with a test plan.
Strong	Detailed testing approach, test strategy, and plans. Documentation shows good overview of components, sensors and control system testing.
Average	Testing approach is presented with sufficient detail, including mention of test strategy and plans. Documentation shows components, sensors and control system testing.
Below Average	Testing approach is presented with little to no detail. No mention of components or sensors testing.
Poor	Testing is done to a certain degree. No components and sensors are tested independently. There are no test plans.
Requirements Not Met	No mention of testing or connection with the system design.

2.1.8 Test Plan & Results (Optional Appendix)

Based off the testing approach outlined in the paper, this appendix showcases the test plan that was developed and the detailed results that came out of testing. Teams should present their plans for testing, including algorithm testing in a virtual environment, component testing in a laboratory setting, sub-system testing in a relevant environment, and full system testing in a pseudo-competition environment. Test set up should be included and results presented. Any design modifications or changes in competition strategy as a result of testing should be discussed.

While this appendix is not required, excellence seen in this section can be eligible for a special judges' award.

The appendix may include detailed documentation covering the following areas:

- *Scope:* Objectives and test cases (this may also specify what was not included in tests)
- *Schedule:* Start/end dates and deadlines

- *Resource and Tools:* Resources and tools needed to conduct tests and assess results
- *Environment:* Description of the test environment, configurations, and availability
- *Risk Management:* Outline potential risks that could occur throughout testing
- *Results:* Detailed outcomes of test cases

2.2 Team Website

Teams are required to submit a website in English that documents their team, vehicle design, and competition approach. To be eligible for full points, teams must submit their website by the deadline found in [Section 1.5](#).

✓ **Top-Scored Website:** Get inspiration from National University of Singapore's first place website from RoboSub 2025. Visit the [website here](#) ↗.

2.2.1 Deliverable Requirements:

1. Website Content: Layout and detailed contents of the website are left for the teams to develop; however, the team website must include:
 - Current team name and contact information
 - Vehicle photos and/or videos
 - Test event summaries showing time in the field (water time, etc.), objectives, and results. This should include simulations and real-world testing.
 - Supporting media, which may include:
 - Instructional/Informative videos
 - Procedures (text, images)
 - Design decision documentation (text, images, videos)
 - Blogs for historical records of build progress
 - List of sponsors with logos
2. Website Quality: Websites are often the first impression of a project. Potential supporters such as supervisors, sponsors, or advisors must find the website visually appealing and easy to navigate. Development of the website should include careful consideration of user experience, including:
 - Written in English, or English translation provided
 - Clear prioritization of key content
 - Site search functionality
 - Basic design elements: contrast, repetition, alignment and grouping to organize/highlight content
 - User accessibility, as defined by the [W3C Web Accessibility Initiative: www.w3.org/WAI](http://www.w3.org/WAI) ↗
 - Cross browser compatibility for modern web browsers (Chrome, Firefox, Safari, MS Edge)

- A mobile friendly display

2.2.2 Scoring Metrics

The website submission is worth a total of **180 points**. The scoring metrics include a scoring weight with guidance for scoring considerations that are provided to the judges during evaluations.

Team Information (20% of score)

Outstanding	Team website includes all required content: team's name and contact information, vehicle photos and test summaries, and a list of team members and sponsors. All mentions of the vehicle are relevant to the current competition year.
Strong	Team website provides a brief introduction to the team, team members and sponsors. There is supporting media on the vehicle.
Average	Team website introduces the team and/or team members.
Below Average	Team website provides little to no information on the team. There is no mention of the vehicle.
Requirements Not Met	The required team information is not included on the website.

Vehicle Design Documentation (40% of score)

Outstanding	Vehicle development and testing process is thoroughly documented with instructional and informative supporting media and historical recording. This could include photographs, diagrams, videos, procedures (text + images), design documentation (text + images + video), or blogs for historical records.
Strong	Good documentation on vehicle development and testing process is provided. Supporting media is accessible.
Average	Vehicle development and testing process is adequately presented with some evidence of supporting media.[L11]
Below Average	Few pictures or videos of the vehicle, but no instructional or informative documentation included.
Requirements Not Met	No visuals or documentation of the vehicle is available on the website.

Website Quality (40% of score)

Outstanding	Website places a heavy emphasis on human factors. Layout is visually appealing, easily maneuverable, and does an excellent job of drawing user's attention to relevant content.
Strong	Website considers user experience. Layout does a good job of drawing user's attention. Users can navigate the site easily and quickly.
Average	Website quality was adequate. Users can navigate the site to find most information.
Below Average	Layout and/or design makes it difficult to find information. Website does not have a user-friendly display.
Requirements Not Met	Website is busy and difficult to read; no guidance on maneuvering site.

2.3 Team Introduction Video

Teams are required to create a video introducing their team members and highlighting their team personality. This video is meant to be a creative showcase of what makes each team unique, such as the mission of the team or the team culture. Teams should consider this video as an “elevator pitch” or project proposal for an opportunity to earn additional funding or support. To be eligible for full points, teams must submit their video by the deadline found in [Section 1.5](#).

 **Top-Scored Video:** Get inspiration from National University of Singapore's first place website from RoboSub 2025. Visit the [video here ↗](#).

2.3.1 Deliverable Requirements

- Video must be conducted in English or include subtitles in English.
- Video must be no more than three (3) minutes in length.
- Video may include graphics, vehicle performance, and/or simulation.
- Videos must be hosted by team. Teams have the choice of hosting on YouTube, Vimeo, or on their Team Website. The video must follow YouTube [Rules & Policies ↗](#), including appropriate music copyright management.

2.3.2 Scoring Metrics

The team video submission is worth a total of **120 points**. The scoring metrics include a scoring weight with guidance for scoring considerations that are provided to the judges during evaluations.

Formatting (10% of score)

Strong	All formatting guidelines are followed. Video is conducted in English or includes English subtitles, video is no more than 3 minutes in length, and video is hosted on the YouTube, Vimeo, or on their Team Website.
Requirements Not Met	Video does not follow formatting requirements.

Video Quality (20% of score)

Outstanding	Visuals immediately draws attention. Overall, the video is solid in frame (not shaky), correctly lighted, in precision focus, appropriately segmented, and visually clear in all respects. Transitions between segments are clear and smooth. The video is less than 3 minutes total runtime.
Strong	Good visual impression. Majority of video is clear, adequately lit, and places people and objects in recognizable scale and perspective. Video segments are generally of the appropriate length, transition well, and are related to each other. Use of video effects is good. Runtime is less than 3 minutes.
Average	Video quality is satisfactory.
Below Average	Frames and segments are shaky, distracting or poorly lit. Some segments are out of focus. Some heavy shadows are obscuring viewpoint. Visual effects are distracting rather than informative. Video exceeds 3 minutes in length.
Requirements Not Met	No focus on visual quality. Video exceeds 3 minutes in length.

Information Organization (25% of score)

Outstanding	Video is a complete introduction of the team makeup including team members, sub-teams, activities, mentors, and major sponsors. Organization of video information is logical and compelling.
Strong	The viewer is left with good understanding of the information shared in video.
Average	Video information is somewhat scattered throughout video, leaving the viewer lacking complete understanding of project.
Below Average	Video provides incomplete information regarding the team members, activities, or progress. The information presented is extraneous, confusing, or low quality.
Requirements Not Met	No organizational strategy is apparent.

Clear and Effective Communication (25% of score)

Outstanding	Effective and compelling use of video medium to communicate the introduction of the team. Easy for non-technical viewer to understand and support. [You're left wanting to learn more.]
Strong	Exhibits moderately compelling use of video medium to communicate the introduction of the team. Strong potential, moderately compelling, mostly understandable to non-technical viewer. [You're left strongly considering to learn more.]
Average	Adequately uses the video medium to introduce the team. Not difficult to understand, but not compelling either.
Below Average	Exhibits some ability to use video to attempt to introduce team and project overview. Difficult for viewer to understand and/or was not compelling. [You're left unenthused.]
Requirements Not Met	Poorly used video medium to convey team introduction. Information was as not clearly understood and was not compelling. [You're left with little information.]

Creativity (20% of score)

Outstanding	Team creativity and enthusiasm is clearly evident in the video. Appropriate use of humor is understated and well done. Video captures user's attention without diminishing or obscuring the information delivered. Effects of careful post-production editing are clear.
Strong	Some creativity has been used throughout video. The visual style and tone are consistent throughout video.
Average	Exhibits a moderate attempt at creativity.
Below Average	Little attempt made to include creative or imaginative ideas in video. Poor visual effects and enthusiasm for the project.
Requirements Not Met	Little imagination or creativity is evident in production. Information is presented lacking enthusiasm.

2.4 Design Strategy Presentation

Teams are required to give a design strategy presentation to a panel of subject matter expert judges. The goal of the presentation is to share the team's system design approach to the challenges presented in the Autonomy Challenge, specifically the capabilities required for each task. The presentation should include:

- a concise description of the team's strategic vision, and
- how the vehicle design compliments the team's goals.

2.4.1 Deliverable Requirements

This presentation must be conducted in English (US) and may include visual aids (e.g., digital slides, poster boards). If digital slides are used, teams must provide their own computer and adapters for an HDMI connector to use the presentation display monitor. Teams receive an assigned 15-minute presentation time. The presentation schedule can be found on the RoboSub webpage: robosub.org/2026 ↗. This presentation includes:

- Team presentation – 10 minutes
- Judges' question and answer – 5 minutes

2.4.2 Scoring Metrics

The design strategy presentation is worth a total of 180 points. The scoring metrics include a scoring weight with guidance for scoring considerations that are provided to the judges during evaluations.

Competition Strategy (30% of score)

Outstanding	Presentation includes a concise description of the team's strategic vision and how the vehicle design compliments their goals. The team clearly explains how they developed their competition strategy.
Strong	Presentation describes their competition strategy and how their vehicle design aligns with meeting their competition goals.
Average	Presentation includes a brief overview of how the vehicle design aligns with the team's competition strategy and goals.
Below Average	Team mentions a competition strategy but no additional details on how it was developed or how it led to their strategic vision.
Requirements Not Met	Team does not mention their competition strategy, vision or how their vehicle design is aligned with vision.

Design Rationale (30% of score)

Outstanding	Team presents their design process and how their decisions relate to their overall competition strategy. Lessons learned from testing or previous competition experience are described, including application throughout the design process.
Strong	Presentation includes a description of the team's design process and includes narrative on how testing or previous experience influenced vehicle design.
Average	Team describes the rationale behind the vehicle design process.
Below Average	Presentation includes mention of the design process, lacking a clear rationale of design choices.
Requirements Not Met	No mention of the team's design process or the rationale behind the design process.

Effective Communication & Professionalism (20% of score)

Outstanding	Presentation materials and team members' knowledge are effective and support the team's message. Team members are engaging, respectful, and professional, while interacting positively with the judges and each other.
Strong	Presentation materials are presented in a professional manner and support the team's message. Presentation is well prepared and appears to be rehearsed in advance.
Average	Presentation materials are presented in a mostly professional manner and support the team's message.
Below Average	Presentation materials and styles are adequate but less than engaging.
Requirements Not Met	The message was not effective, and the presentation was not organized.

Judge Questions & Dialogue (20% of score)

Outstanding	The team effectively uses evidence, experience, and research from their project to inform responses to all questions and discussion posed by the judges.
Strong	The team responded professionally and knowledgeably to judges' questions.
Average	The team responded adequately to most or all of the judges' questions, mostly interacting with courtesy and professionalism.
Below Average	The team did not provide sufficient answers to the judges' questions and interacted with minimal courtesy and professionalism.
Requirements Not Met	Team members were not able to respond to many or all questions and did not take the initiative to engage in dialogue with the judges.

2.5 System Assessment

Judges inspect the team's vehicle and assess technical design, technical innovation, and craftsmanship of the design. Team members should be present to answer technical questions posed by the judges during this inspection and be prepared to explain their design strategy and how decisions made impacts on the technical design, functionality, and craftsmanship.

Teams receive an assigned 15-minute slot. The assessment schedule can be found on the RoboSub webpage: robosub.org/2026 ↗.

2.5.1 Deliverable Requirements

Team members are required to be present to answer technical questions posed by subject matter expert judges during this inspection and be prepared to explain their design strategy and how decisions made impact the technical design, functionality, and craftsmanship.

2.5.2 Scoring Metrics

The system assessment is worth a total of **180 points**. The scoring metrics include a scoring weight with guidance for scoring considerations that are provided to the judges during evaluations.

Technical Design (45% of score)

Outstanding	Design and implementation of systems and subsystems are well aligned with team's strategy, design decisions, and engineering principles. Clear and thoughtful design choices are evident in the technical functions, key decisions, and testing regimen.
Strong	Good and knowledgeable rationale and execution of design selections made, aligning with team's strategy, design decisions, and engineering principles.
Average	Adequate explanation of technical design decisions, equipment selections, and testing regimen, mostly evident in the vehicle and subsystems.
Below Average	Rationale of technical design is briefly covered with minimal alignment with team's strategy, design decisions, and engineering principles.
Requirements Not Met	Design and implementation of systems and subsystems are not aligned with team's strategy, design decisions, and engineering principles.

Innovation (30% of score)

Outstanding	Full system demonstrates creative and innovative solutions by applying existing technology in novel ways within the system, using existing technology in a previously unintended way, or creating new technology or products incorporated into the system.
Strong	Clear evidence of innovative approaches across multiple sub-systems. Research and testing were conducted throughout the development process.
Average	There is moderate evidence that creative and innovative solutions were incorporated into system to improve performance.
Below Average	Little evidence of creativity or innovation in design choices throughout the system.
Requirements Not Met	No technical innovation noted.

Craftsmanship (25% of score)

Outstanding	System is assembled with exquisite care and thoughtful attention to detail and aesthetics. Construction and improvisations are neatly executed to maintain high levels of functionality, durability, and adherence to the team's design philosophy. Any vehicle adornment demonstrates creativity, originality, etc.
Strong	System is assembled with care and attention to detail and aesthetics. Construction and improvisations maintain acceptable levels of functionality, durability, and adherence to the team's design philosophy.
Average	System is assembled to execute acceptable levels of functionality, durability and adherence to team's design philosophy.
Below Average	Minimal evidence that system is assembled with care and attention to detail and aesthetics. Adherence to team's design philosophy is vague and unclear.
Requirements Not Met	Evident hazards or potential hazards throughout the system. The system was assembled with minimal care and attention to detail. Little to no attention to aesthetics.

Section 3: Autonomy Challenge

This section includes detailed requirements and instructions for the autonomy challenge portion of the competition.

These challenges showcase AUV performance through autonomous behaviors designed to represent research and real-world applications.

[3.1 Mandatory Activities](#)

[3.2 Task Descriptions](#)

[3.3 Vehicle Operations](#)

[3.4 Competition Sequence of Events](#)

3.1 Mandatory Activities

Before entering the Autonomy Challenge courses, teams must demonstrate their AUV adheres to the vehicle requirements outlined in [5.3 Vehicle Requirements](#), and the ability to safely control their AUV with the following mandatory activities: static safety inspection and weight measurement

3.1.1 Static Safety Inspection

Before operating in the water, all systems must pass a safety inspection, as outlined in [5.2 Safety Requirements](#). The Course Director may disqualify any vehicle that is deemed unsafe. The system requirements are listed in [5.3 Vehicle Requirements](#).

3.1.2 Weight Measurement

Vehicles are weighed before each semi-finals and finals run. Teams transport the vehicle on their cart to the scale for weight measurement. The table below shows the bonuses and penalties associated with a vehicle's weight in air.

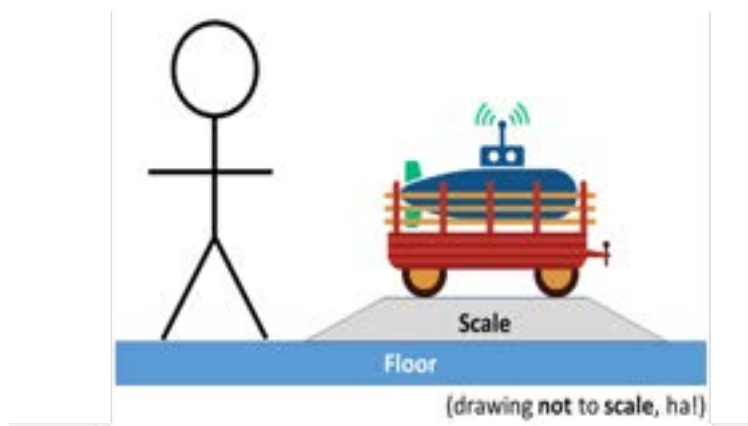


Figure 1: Example Vehicle Weight Measurement

Table: Vehicle weight in air with Bonus or Penalties

WEIGHT	BONUS	PENALTY
AUV Weight > 60 kg (AUV Weight > 132 lbs)	N/A	Disqualified!
60 kg ≥ AUV Weight > 38 kg (132 lbs ≥ AUV Weight > 84 lbs)	N/A	Loss of: -(250 + 11*(Weight (kg) – 60)) -(250 + 5*(Weight (lb) – 132))
38 kg ≥ AUV Weight > 22 kg (84 lbs ≥ AUV Weight > 48.5 lbs)	Bonus: 4.4*(38 - Weight (kg)) <u>2*(84 - Weight (lb))</u>	N/A
AUV Weight ≤ 22 kg (AUV Weight ≤ 48.5 lbs)	Bonus: 80 + 2.2*(22 - Weight (kg)) 80 + (48.5 - Weight (lb))	N/A

Vehicle Weight Example Calculations:

✓ **Vehicle Weight: 50kg**

$$-(250+11(50-60)) = -140$$

✓ **Vehicle Weight: 25kg**

$$4.4(38-25) = 57$$

✓ **Two Vehicles - #1) 45kg, #2) 18kg**

- Vehicle #1, 45kg: $-(250+11(45-60)) = -85$
- Vehicle #2, 18kg: $80+2.2*(22-18) = 89$
- Total points: $-85 + 89 = 4$ points

3.2 Task Descriptions

This section provides details of the tasks in the Autonomy Challenge. Teams are encouraged to develop a strategy approaching these tasks that best suits their vehicle(s). The launch point, gate, or any of the tasks are placed such that no three elements are along a line.

Restore and Recovery

A storm swept through the area, leaving behind damaged infrastructure, disrupted communication, and environmental hazards. Vehicles are deployed to demonstrate how coordinated action can turn disaster into resilience and take on one of two roles: **Survey & Repair** or **Search & Rescue**.

- **Survey & Repair:** Vehicles are deployed for damage assessment to inspect the area and repair infrastructure.
- **Search & Rescue:** Vehicles search the debris armed with supplies to restore safety and functionality.

3.2.1 Heading Out (Coin Flip)

At the start of a run, teams may orient their AUV in any direction from the designated starting location. All vehicles must begin the run on the surface, and submerge before leaving the start zone.

Before the start of a run, and for additional points, teams may request a coin flip which determines the AUV's starting orientation:

- If the coin lands on **HEADS**, the AUV is positioned approximately parallel to the gate.
- If the coin lands on **TAILS**, the AUV is positioned with its tail approximately facing the gate (the AUV is backward).

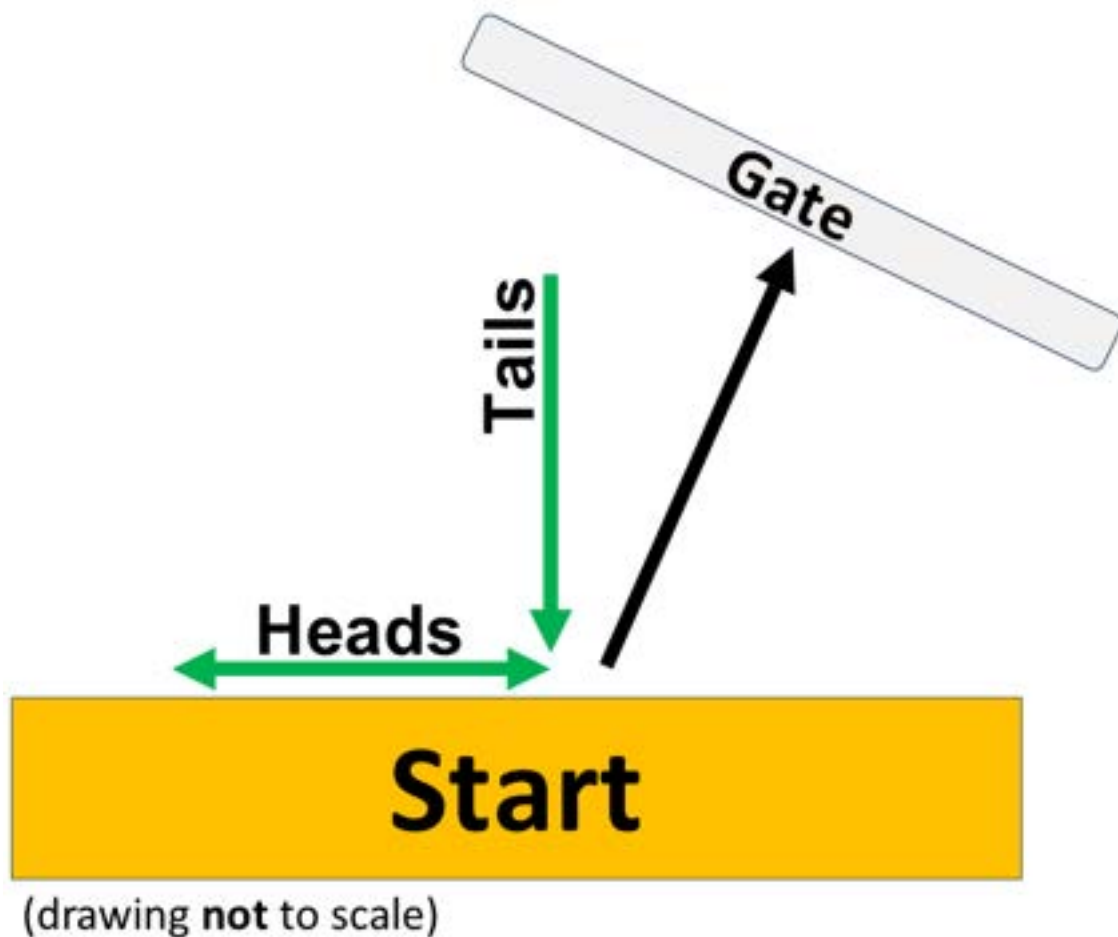


Figure : Heading Out

3.2.2 Task 1 - Begin Assessment (Gate)

Head out to assess the environment.

The task consists of a gate built from PVC pipe floating just below the surface and moored to the bottom. Surrounding the vertical legs of the pipe are 3-inch wide panels made from **BLACK** and **RED** corrugated plastic sheet, attached to make a box around the pipe. On the right-hand side, **RED** covers the upper half (Red, Right, Above) and **BLACK** covers the bottom half. On the left-hand side **BLACK** covers the upper half and **RED** covers the lower half.

The gate is built from PVC pipe and 3-inch boxes made from corrugated plastic sheet. It is buoyant, floating just below the surface and moored to the bottom. The boxes are colored **BLACK** and **RED**. **RED** is on top on the right-hand side (Red, Right, Above). The AUV can pass through the gate at any depth from the floor to just below the gate.

A 2-inch **RED** corrugated flat sheet is used to divide the gate in half. An image of a 🏠 / 🚧 (Survey & Repair) on one side (could be either side), an image of 🚑 / 🚒 (Search & Rescue) on the other side. The AUV chooses a role by passing under a specific side.

- **Survey & Repair:**  / 
- **Search & Rescue:**  / 

The AUV can pass through the gate at any depth from the floor to just below the gate. The AUV takes on the role of the sign on the side through which it passes.

Teams can gain extra points by passing through the gate with “style”. For every 90° change in orientation, the AUV increases the accumulated points. However, returning to the last previous orientation won’t count. I.e. an AUV that rolls 90° and then back to 0° would not get points. Roll and Pitch are worth more than Yaw.

Capability Matrix

Maintain depth and heading, visual identification

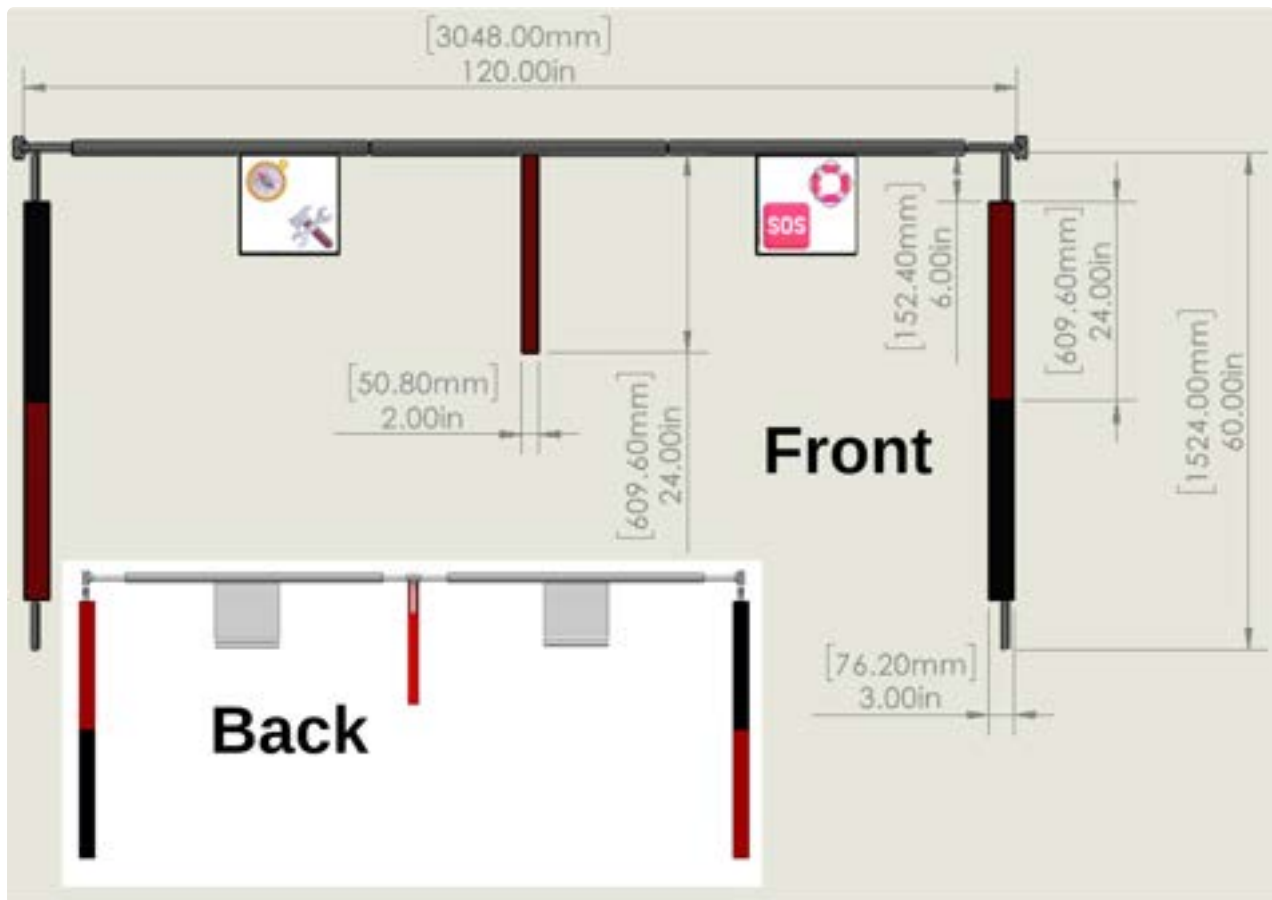
- **Core:** Pass through the gate.
- **Advanced:** Coin flip determines orientation of the vehicle at the start.
- **Disruptive:** Random role assignment, either by a coin flip or visual indicator.

 In the event the visual indicator is not available, a coin flip will be used to randomly assign a role to the AUV before it starts its run.

Scoring Quest

- Pass through the gate
- Maintain control
- Coin flip (heading)
- Coin flip (role)
- Style: Yaw, Roll/Pitch

Task



Task Elements

The table below contains descriptions of the task elements for this task. Task design files can be found in [RoboSub Data Sharing](#).

Task Element	Description	Color	Height
Gate	¾ in, ½ in PVC, Foam, 3 in. Box Corrugated plastic	White / Black / Red	120 in x 60 in (3 m x 1.5 m)
Gate Divider	2" Flat plate	Red	24 in (610 mm)
	Role: Survey & Repair	Vinyl print Design files	12 in x 12 in (305 mm x 305mm)
	Role: Search and Rescue	Vinyl print Design files	12 in x 12 in (305 mm x 305 mm)

3.2.3 Task 2 - Avoid Debris (Slalom)

Navigate a channel that is blocked with debris.

The task consists of sets of vertical **RED** and **WHITE** PVC pipes moored at different heights to the floor, and floating vertically. They are arranged with **WHITE** on the left, **RED** in the middle, and **WHITE** on the right. There are three sets of pipes, and the AUV earns points for each set that is successfully navigated.

The AUV will obtain more points for staying on the same side of the red pipe when it passed through the gate. I.e. if the AUV passed with the red gate divider on the right, it should pass through the Slalom with the red pipe on the right. The AUV will obtain more points for staying within the area of the pipes (not above, not below). As long as a part of the AUV breaks the plane of the pipes, it is considered inside.

Capability Matrix

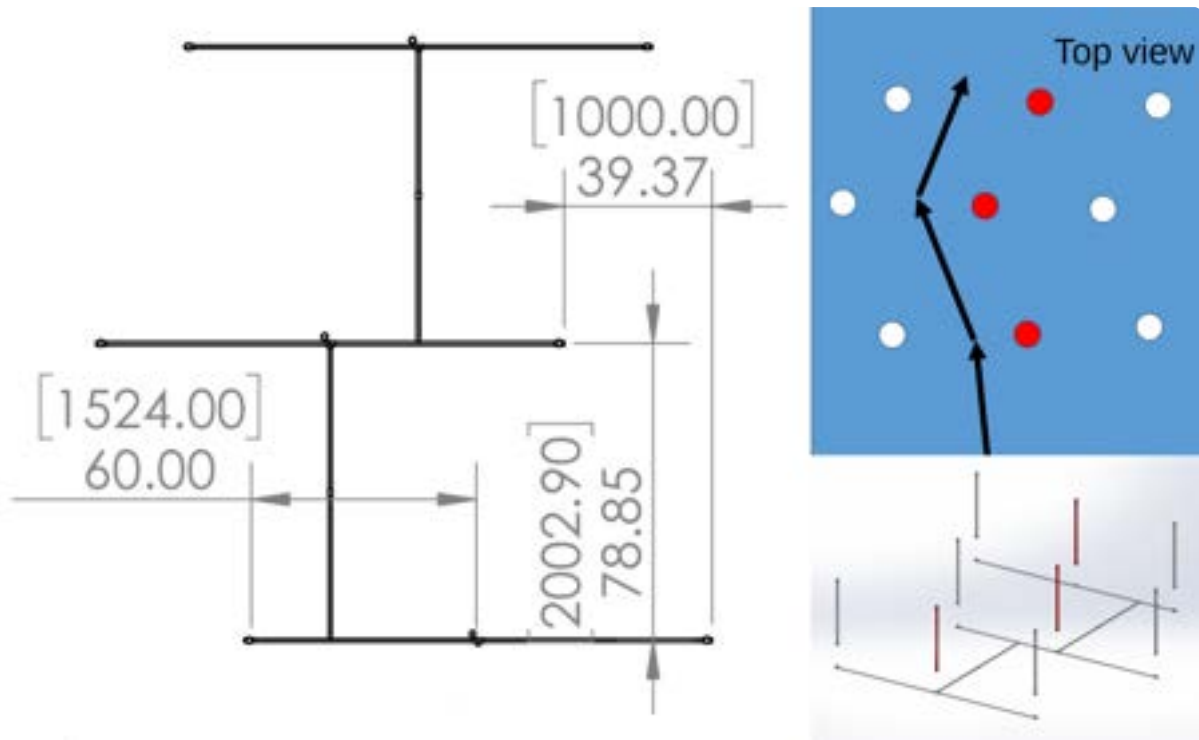
Adjust depth, course correction, visual perception

- **Core:** Identify and stay within the slalom
- **Advanced:** Navigate the correct side
- **Disruptive:** None

Scoring Quest

- Navigate the debris: any, correct side
- Correct depth

Task



Task Elements

The table below contains descriptions of the task elements for this task. Task design files can be found in [RoboSub Data Sharing](#).

Task Element	Description	Color	Height
Pipes	1 inch PVC	White / Red	3 ft (0.9m)

3.2.4 Task 3 - Recon (Bins)

Recon the area to determine what assistance to provide.

This task consists of a 3D pipeline made from PVC supported off the bottom of the pool. On the sides of the pipeline are four bins. Two for the **Survey & Repair** role and two for the **Search & Rescue** role. Inside the bins will be images representing each role:

- **Survey & Repair:** 🔥
- **Search & Rescue:** 🚒

Near each bin on the pipeline will be a light and a magnetic detector for the AUV to interact with. At the start of a run, the light will be turned on signaling the need for repair or rescue.

The AUV will obtain points for dropping up to two (2) markers into the bin, based on where a marker finally comes to rest. More points are awarded for dropping a marker in each of the bins corresponding to the AUV's role, one marker in each of the two bins. Additional points are awarded for interacting with up to two (2) magnetic detectors on the pipeline and turning the lights off.

 **Now Available** | [Build Guide: Underwater Magnetically Activated Light](#) ↗

Capability Matrix

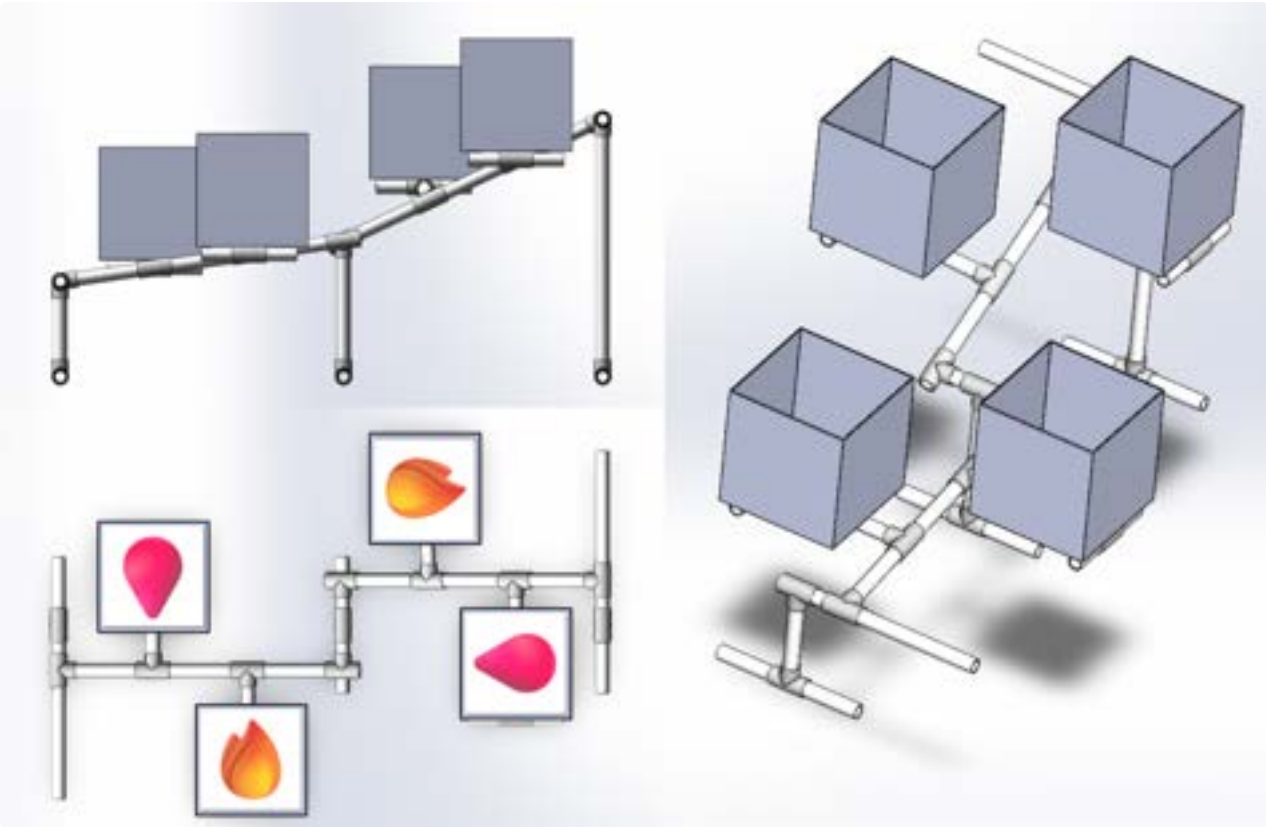
Station keep (horizontal), Visual identification, (maybe) Interaction

- **Core:** Drop markers in the bin
- **Advanced:** Drop markers in the correct bin
- **Disruptive:** Interact with magnet to turn off light

Scoring Quest

- Drop marker(s) in: any, correct bin
- Turn off light

Task



Task Elements

The table below contains descriptions of the task elements for this task. Task design files can be found in [RoboSub Data Sharing](#).

Task Element	Description	Base Dimensions
Bin	Bin with insert	CleverMade Collapsible Milk Crate 25L (Amazon)
 	Vinyl Print Design files	12 in x 12 in (305 mm x 305 mm)
Magnetically Activated Light	Build Guide	

3.2.5 Task 4 - Deploy (Torpedoes)

Provide necessary assistance.

This task consists of one vertical board with images on the front side,   for **Survey & Repair** and   for **Search & Rescue**. There are two different versions of the board. There are two different size openings.

Points are awarded for firing torpedoes through any opening. A torpedo must pass through the opening for full points. Partial points are awarded if the torpedo touches the board without passing through. Maximum points are awarded for firing a torpedo through the larger opening ( ) and then the smaller opening ( ). Additional points are awarded for firing torpedoes further away from the board: far (1 ft, 0.3m) and farther (1.5 ft, 0.46m).

Capability Matrix

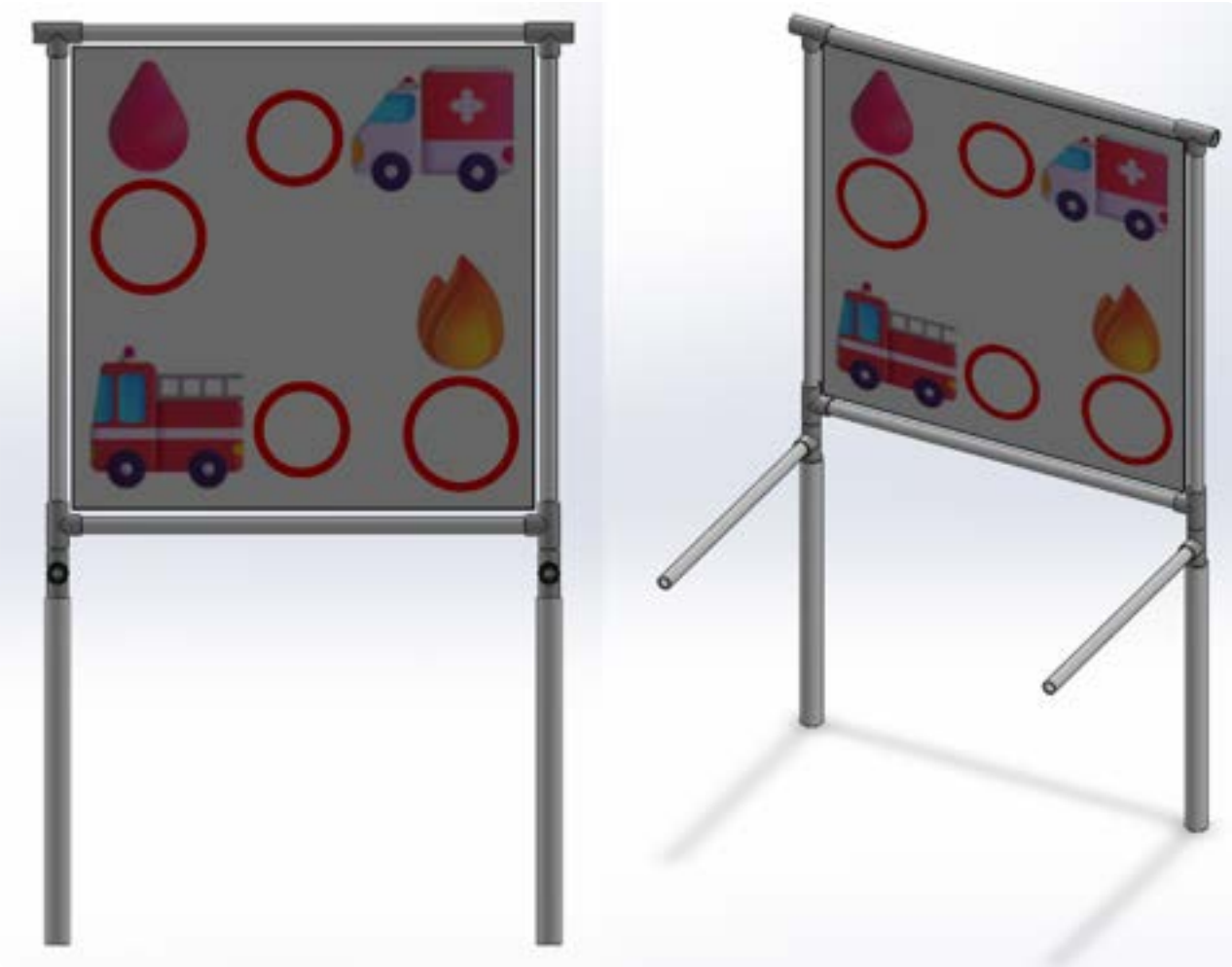
Acoustic localization, station keep (horizontal/vertical), visual identification

- **Core:** Fire torpedo through any opening
- **Advanced:** Fire torpedoes through opening in the correct sequence (large, small)
- **Disruptive:** None

Scoring Quest

- Fire torpedo through any opening
- Fire torpedo through correct sequence
- Fire from far, farther

Task



Task Elements

The table below contains descriptions of the task elements for this task. Task design files can be found in [RoboSub Data Sharing](#).

Task Element	Description	Base Dimensions
   	Vinyl print images and openings, Corrugated plastic backing Design files	2 ft x 2 ft (0.6m x 0.6m)

3.2.6 Task 5 - Restore (Octagon)

Restore vital infrastructure and health.

A 9 ft (2.7m) diameter octagon floats on the surface and an acoustic pinger, located on the floor near the center of the octagon, guides the AUV to this task. Hanging from the octagon, facing inward, are images of , , , and . Located in the center of the octagon is the Resupply table. On the table are two different items for each role: **Survey & Repair** has  and ; **Search & Rescue** has  and . Along two opposite edges is a basket to place the items. At the bottom of the **Survey & Repair** basket is  and at the bottom of the **Search & Rescue** is .

Points are awarded for surfacing inside the octagon and for surfacing with each item (stay inside the octagon to continue your run). Points are awarded for facing any image hanging from the octagon, with maximum points for facing the correct icon based on the role and items in the basket. With one item in the basket face  or . With two (or more) items in the basket face  or . Points are awarded for moving the items to any of the baskets. Maximum points are awarded for placing the correct items in their corresponding basket based on role.

Extra points are awarded for the AUV vehicle rotating the same number of turns as the items collected in the baskets. (i.e. three items in the basket? rotate three times.)

Capability Matrix

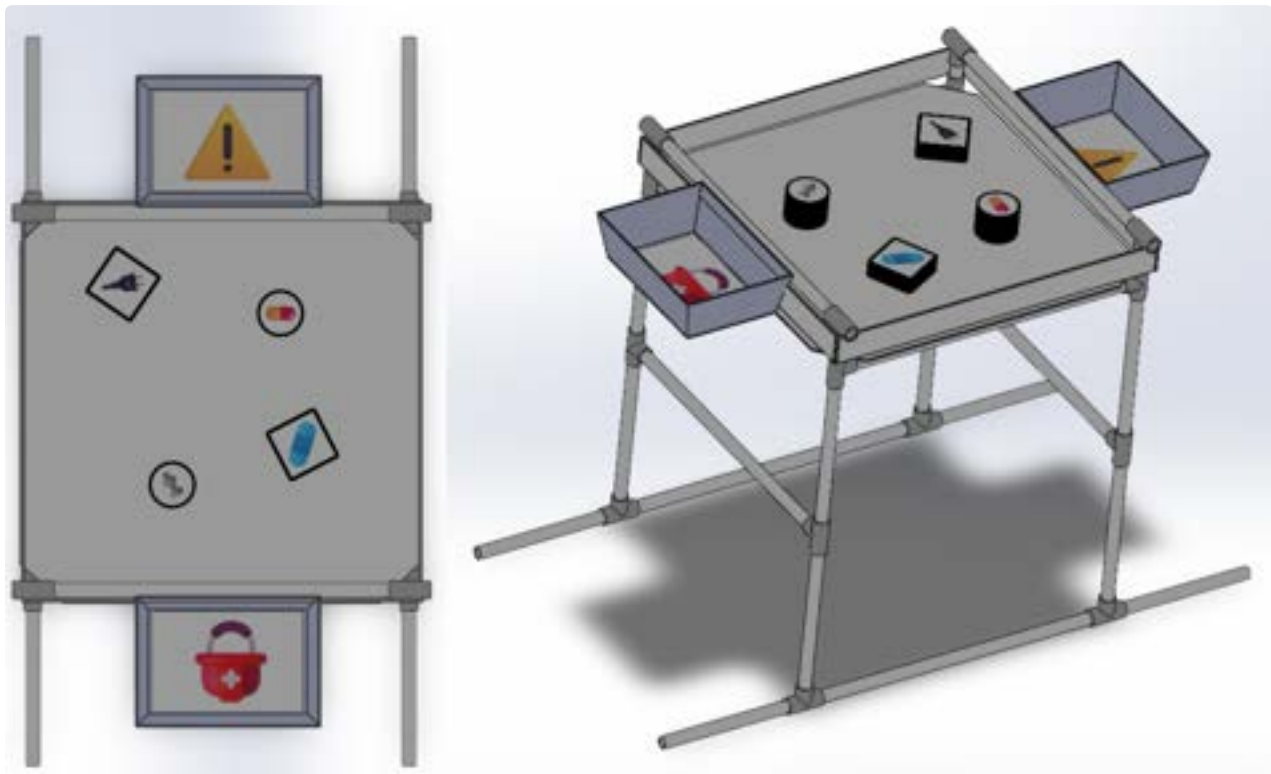
Acoustic localization, station keep (horizontal/vertical), visual identification, manipulation

- **Core:** Surface in octagon
- **Advanced:** Pick up and deliver at least one object to any basket
- **Disruptive:** Face correct image

Scoring Quest

- Surface in area
- Surface with object
- Drop object
- Place object in any / correct basket
- Yaw correct number of times for object in basket
- Face any image / correct image
 - Correct image is dependent on number of objects in basket
 - 1 item, point to :  or 
 - 2 item, point to :  or 

Task



Task Elements

The table below contains descriptions of the task elements for this task. Task design files can be found in [RoboSub Data Sharing](#).

Task Element	Description	Base Dimensions
Octagon	½ in PVC Surface marker	9 ft diameter (2.7 m)
Images	Vinyl print Design files	12 in x 12 in (305 mm x 305mm)
Table	½ in PVC Table containing samples and collection bins	2 ft x 2 ft (0.6 m x 0.6 m)
Objects	Cylindrical and Box-like objects to pick up with images on the top	• Loretoy 4oz plastic jars with lids (2.76" dia x 1.97" tall) • Satinior small clear plastic bead storage container (3.3 x 3.3 x 1.2")
Basket	Collection baskets	Netany Plastic Storage Baskets (Amazon)

3.2.7 Task 6 - Return Home

At the end of the run, while underwater, the AUV passes back through the start gate.

3.2.8 Path

The path markers are ~4 feet (~1.2m) long by 6 in (15 cm) wide. The Path is colored **ORANGE**. Each path markers is placed directly after the current task and points to the next task. The path is a straight segment. No points are awarded for following the path, the path is intended to help guide the AUV to the next task.

There are two path markers to aid in navigation. One path marker is positioned at the gate that points to the *Avoid Debris (Slalom)* task. From the *Avoid Debris*, the second path points to *Recon (Bins)*. Those are the only path segments which can be used to visually orient the AUV to the next task.

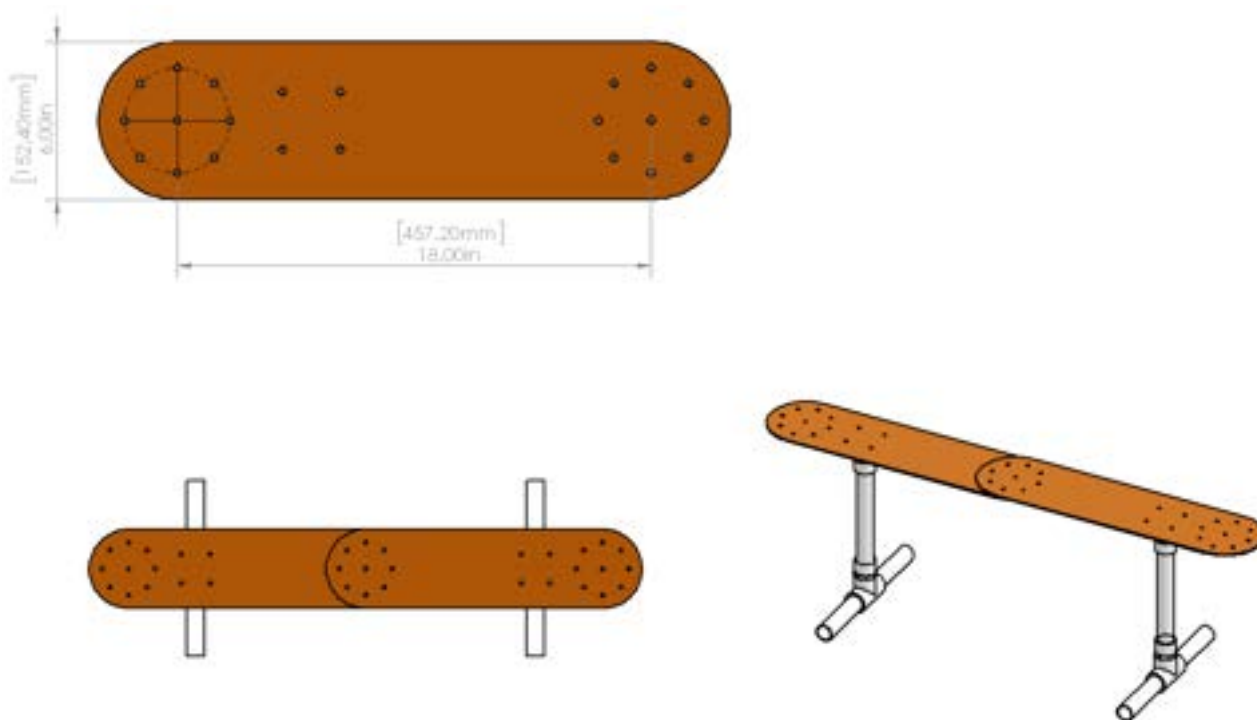


Figure : Path marker

3.2.9 Pinger

For each pinger task, the pinger is located very close to the task (sometimes next to, sometimes in the center). No points are awarded for following/finding a pinger, the pinger is intended to help guide the AUV to the task.

There are two pingers to aid in navigation. The first pinger is positioned at *Deploy (Torpedoes)*. The second pinger is located at *Restore (Octagon)*.

See section [5.4.3 Pingers](#) for more information.

Build Guide: Underwater Magnetically Activated Light

Overview

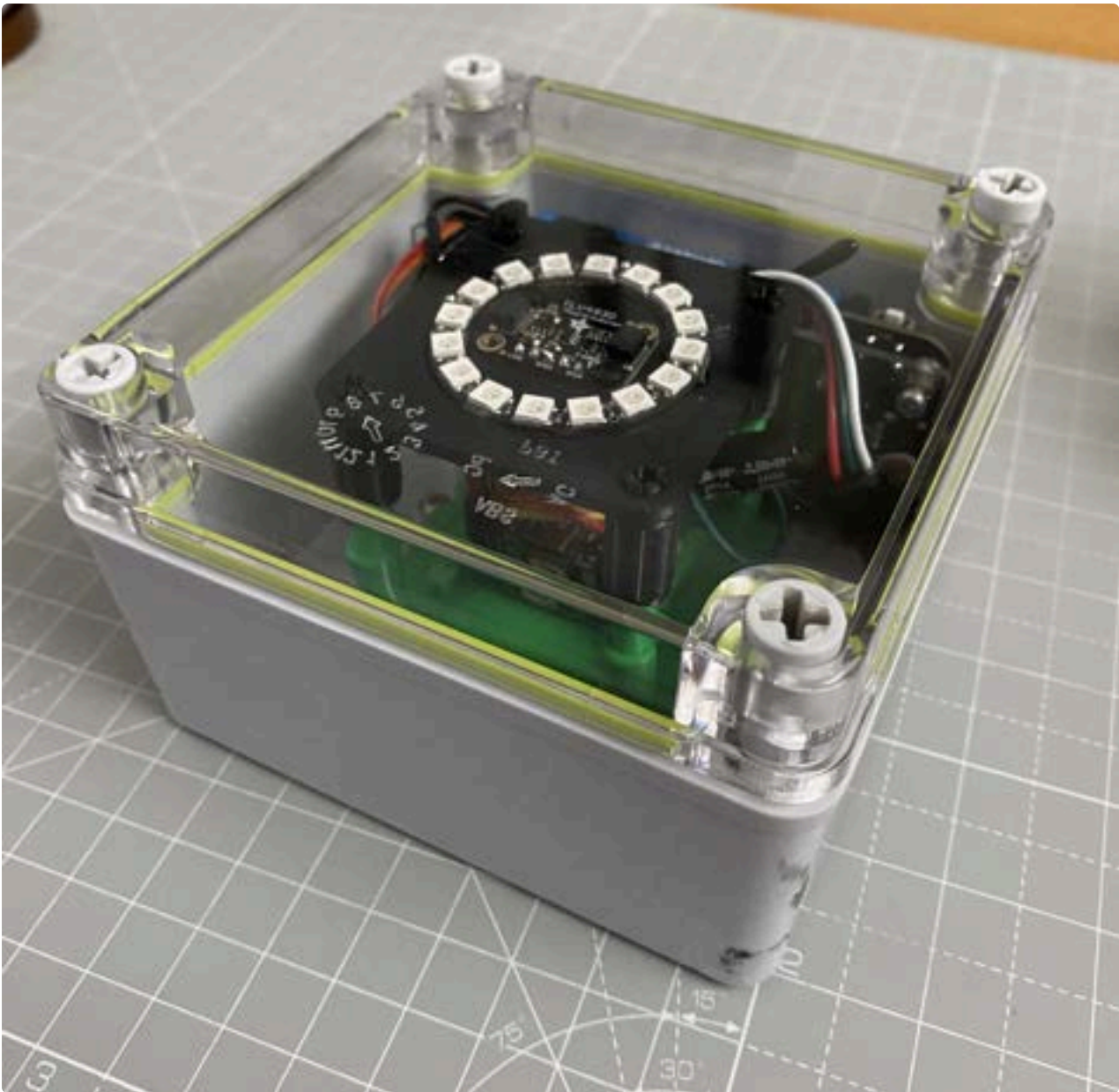
The Underwater Magnetically-Activated Light is a test unit with the same magnetometer and LEDs as the Pipeline Sensor Lights used in RoboSub 2026 and RobotX 2026.

This is presented as a standalone unit that teams can build to practice and train their systems. This unit is battery powered, whereas the competition unit is powered from shore.

This unit does not have to be duplicated exactly. The components that should be the same are the magnetometer and the LED ring.



Modeled Competition Unit (Node)



Fully Assembled Test Unit

Key specs:

- Magnetometer
 - Adjustable distance from outside of the top cover: 0.2" (5mm) to 0.5" (13mm)
 - Centrally located, inside the LED Ring
- LED Ring
 - 16 WS2812B LEDs
 - Full brightness
 - RED or GREEN

Triggering Conditions

- TDB mT
- Magnet held at magnetometer for 0.5 seconds

Source Code

GitHub repository: [Underwater-Magnetically-Activated-Light](#) ↗

Parts List

Description	Qty	Vendor Link
Enclosure, ABS Plastic Electrical Box 4.9 × 4.9 × 3 inch(125 * 125 * 75mm) See note regarding seal and testing	1	Amazon.com ↗
16-LED Ring, RGB WS2812	1	Pack of 1 - Amazon.com ↗ Pack of 5 - Amazon.com ↗
Magnetometer, Adafruit TLV493D Triple-Axis Magnetometer, Part number 4366	1	Adafruit ↗ Amazon.com ↗ DigiKey ↗
Microcontroller/Adapter, AITRIP 2 Sets ESP32-C3 MINI Development Board	1	Amazon.com ↗
Thermistor, NTC Thermistor 10k Bead with wires	1	DigiKey ↗
Power Bank, DFRobot, DFR0969 Two x 18650 battery holder power bank	1	DigiKey ↗
18650 3.7V Lithium Battery	2	Self source
Capacitor, 1000uF 16V 10×17mm Electrolytic Capacitor	1	15-pack Amazon.com ↗ DigiKey search ↗
Resistor, 10KΩ ¼ Watt	1	Self source
Resistor, 470Ω ¼ Watt	1	Self source
Component Mounting Plate, 2.5 mm (0.09") thick X 108 mm X 115 mm Acrylic sheet	1	PDF Mechanical Drawing ↗ STEP File ↗
3D Printed Base Plate (ESP32-Sensor Mount Support Base)	1	STEP File ↗
3D Printed Sensor/LED Mounting Plate Adjustment Standoff	4	STEP File ↗
3D Printed Sensor/LED Mounting Plate	1	STEP File ↗

LED Supply Wiring Harness (male connector) BTF-LIGHTING JST SM 3 Pin Connectors for WS2812B	1	20 Pair Pack Amazon.com ↗ Contains male and female connectors
LED Driver Wiring Harness (female connector) BTF-LIGHTING JST SM 3 Pin Connectors for WS2812B	1	Use above link
Thermistor Wiring Harness	1	Uses 10K resistor (self source) and female Dupont connector terminals See photo in this guide
ESP32 Power/Ground Jumpers, Dupont Female-Female jumper wires 2 (PWR/GND) x 20 cm long. Can substitute with other wires	1	Reference 240 pcs set Amazon.com ↗ Check DigiKey, Mouser, Adafruit, etc.
Magnetometer Jumpers, Dupont Female-Female jumper wires 4 (PWR/GND/SDA/SCL) x 10 cm long. Can substitute with other wires	1	Use above link
M3 × 8mm Long Pan Head Machine Screw	4	Comes with DFRobot power bank
M3 × 12 mm Long Flat Head Machine Screw, steel or stainless steel	4	Reference Amazon.com ↗ May be available at local hardware stores in smaller quantities
M2 × 5 mm Long Nylon Pan Head Machine Screw	2	Reference Amazon.com ↗ May be available at local hardware stores in smaller quantities
M2 Nylon Hex Nut	2	Comes with kit linked above May be available at local hardware stores in smaller quantities
M3 Nylon Insert Locking Hex Nut, steel or stainless steel	4	Assorted kit Amazon.com ↗ May be available at local hardware stores in smaller quantities

Male pin headers, 1-position.
Standard 2.54mm pitch type
compatible with Dupont headers

7

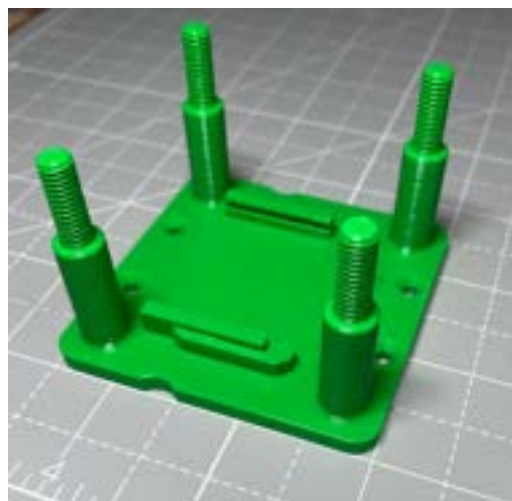
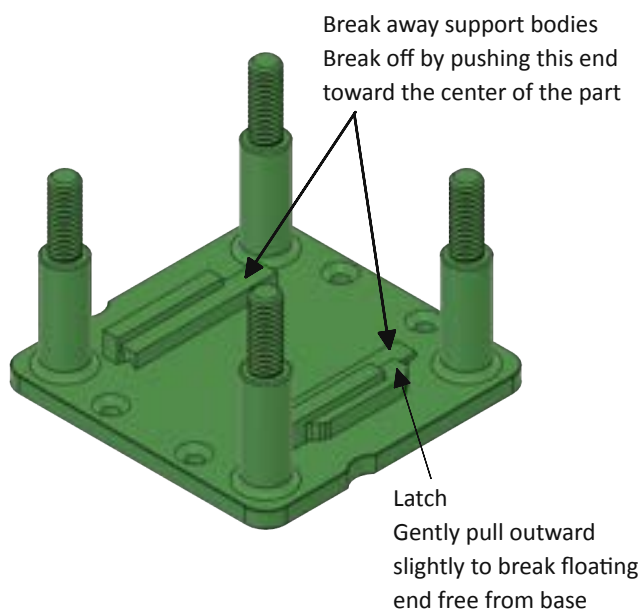
Reference [Amazon.com](https://www.amazon.com) ↗
Wires may be soldered directly
LED ring instead of using header
pins on ring and Dupont
terminals on wires

Parts Notes:

The following parts may be substituted:

1. The **enclosure** listed is IP67 and was tested at 10 psig for 4 hours.
2. The **microcontroller** was chosen for size and convenience connecting the wires.
3. The **thermistor** is optional. The thermistor is used to measure the internal air temperature and the LEDs are powered off at a set threshold in code.
4. The **capacitor** can be substituted for other physical sizes and ratings; 470uF to 1000uF is recommended.
5. The **3D printed parts** may be redesigned or eliminated completely. The LED ring and magnetometer can be taped to the enclosure cover.
6. The **power bank** was leftover from another project and is well suited, but may be easily substituted.
7. All **wiring harnesses** may be substituted. The LED power and driver wiring harnesses are standard LED connector pigtails

3D Printed Part Files



Base Plate (ESP32-Sensor Mount Support Base)



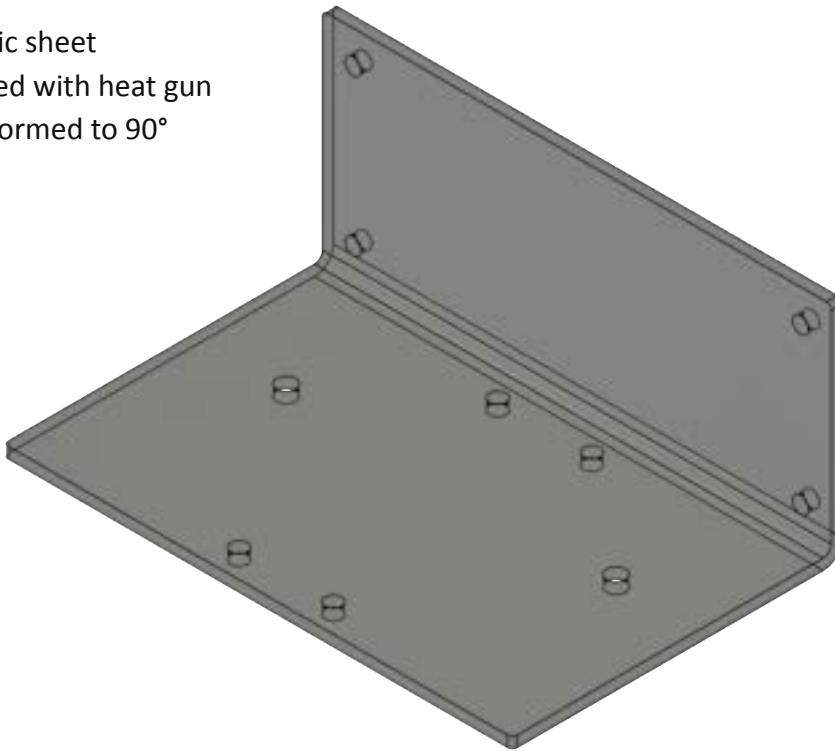
Sensor/LED Mounting Plate Adjustment Standoff
4 Required



Sensor/LED Mounting Plate

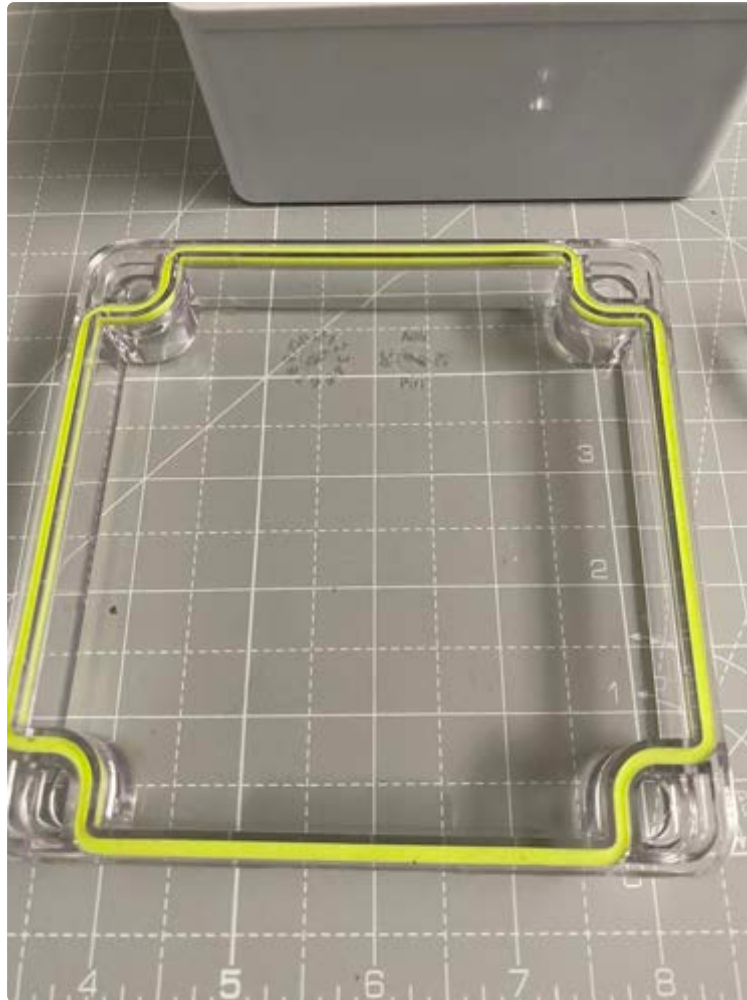
Fabricated Parts

Acrylic sheet
Heated with heat gun
and formed to 90°



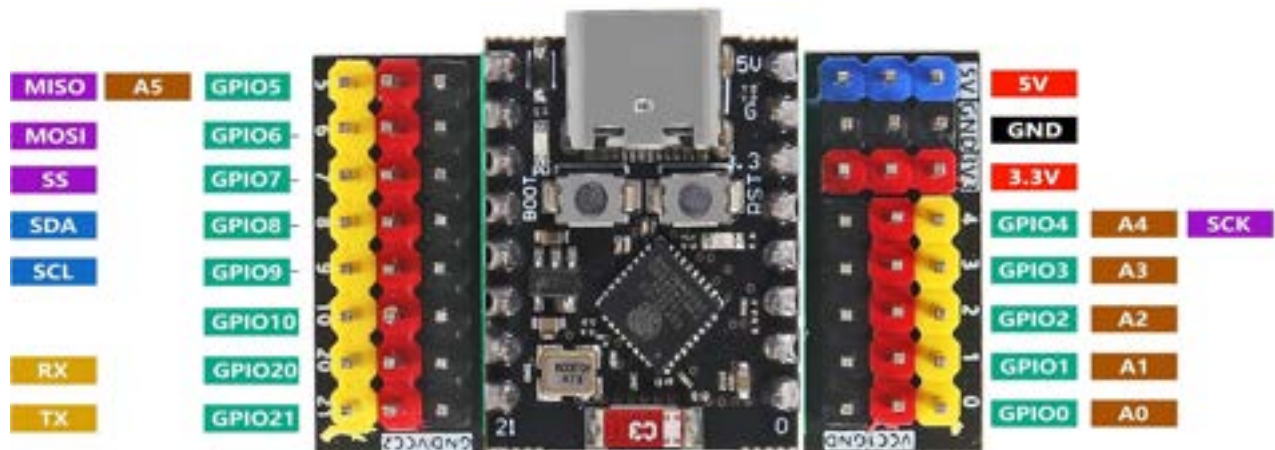
Component Mounting Plate

Enclosure - Additional Information



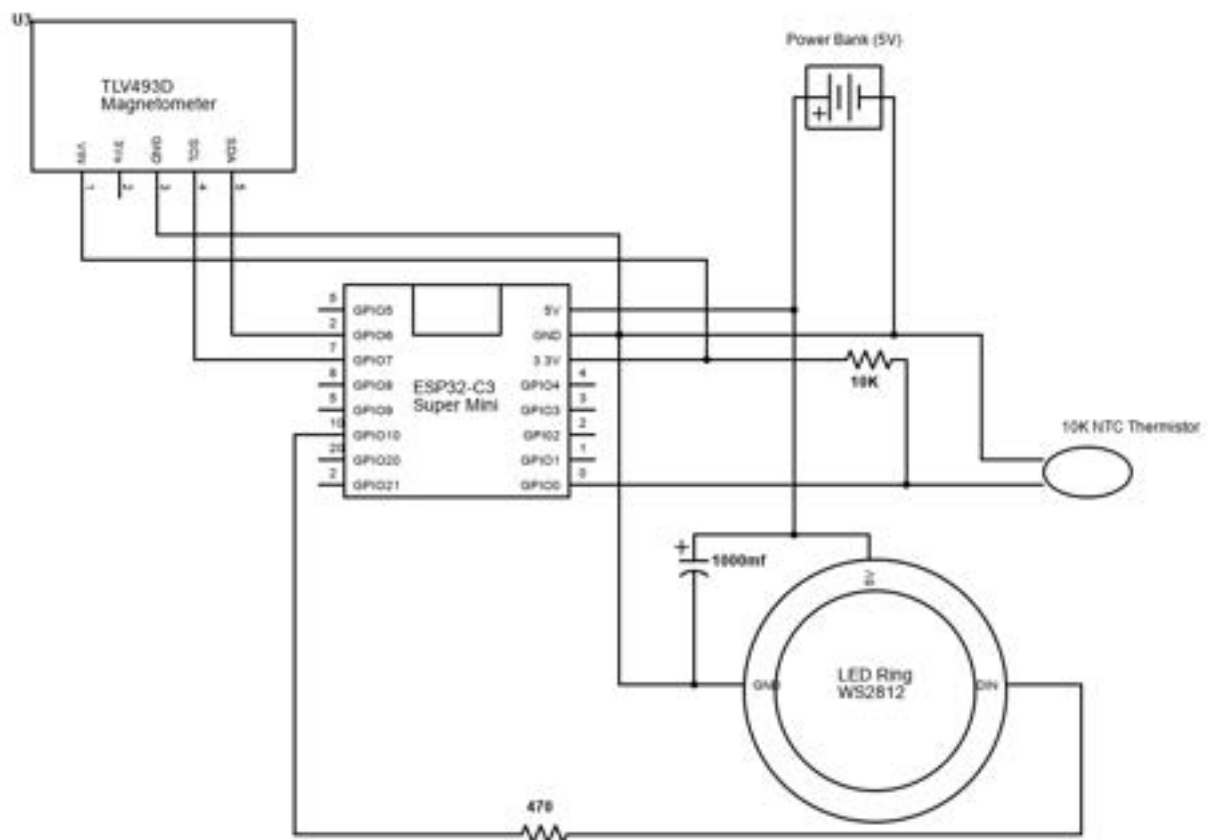
Various enclosures were tested. Only the enclosures with silicone seals will seal against water pressure. Enclosures with black foam seals leak at low pressures. The enclosure referenced in the parts list was tested at 10 psi (equivalent of 23 feet in freshwater) for 2 hours. Longer period tests were performed at lower pressures.

ESP32

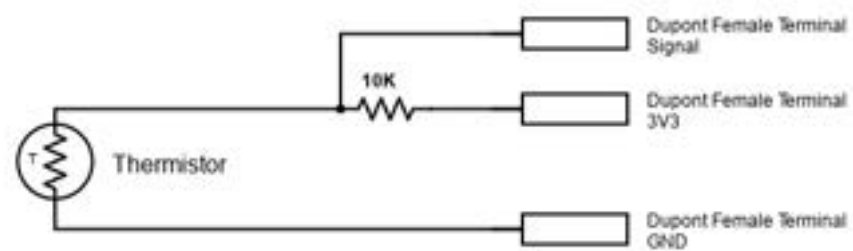


System Schematic

Note: SDA and SCL on the ESP32 were not used for the magnetometer due to a library conflict. The magnetometer's SDA and SCL pins are connected to GPIO6 and GPIO7 respectively and configured in the source code.



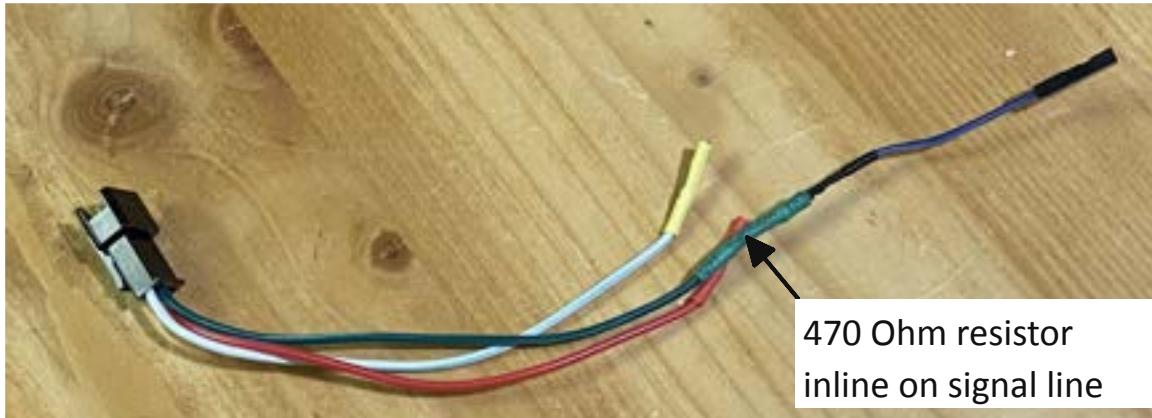
Solder pin headers as shown



Thermistor Schematic



Assembled Thermistor



LED Supply Wiring Harness



LED Driver Wiring Harness



Magnetometer Jumpers



ESP32 Power/Ground Jumpers



ESP32 Installed on Base

Solder two sets of male pin headers to the 5V rail of the power bank.
The photo shows three sets. Add more sets as needed for additional power connections.



Power Bank

Remove the power bank's base plate if it was pre-installed.

Mount power bank on outside of the short flange of the base plate with screws supplied with the power bank.

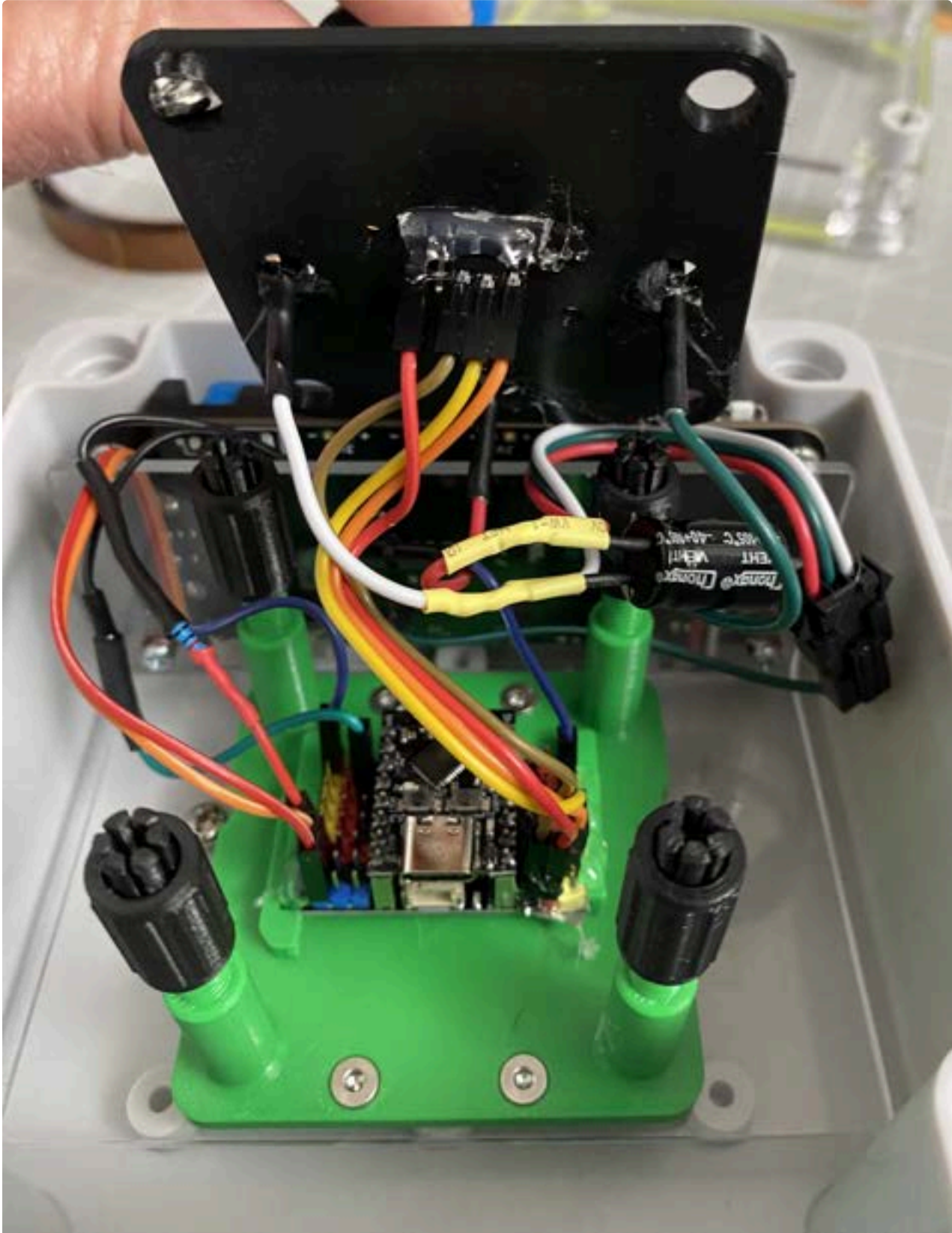
Mount the magnetometer board to the sensor/LED mounting plate using two M2 × 5 nylon pan head machine screws and hex nuts.

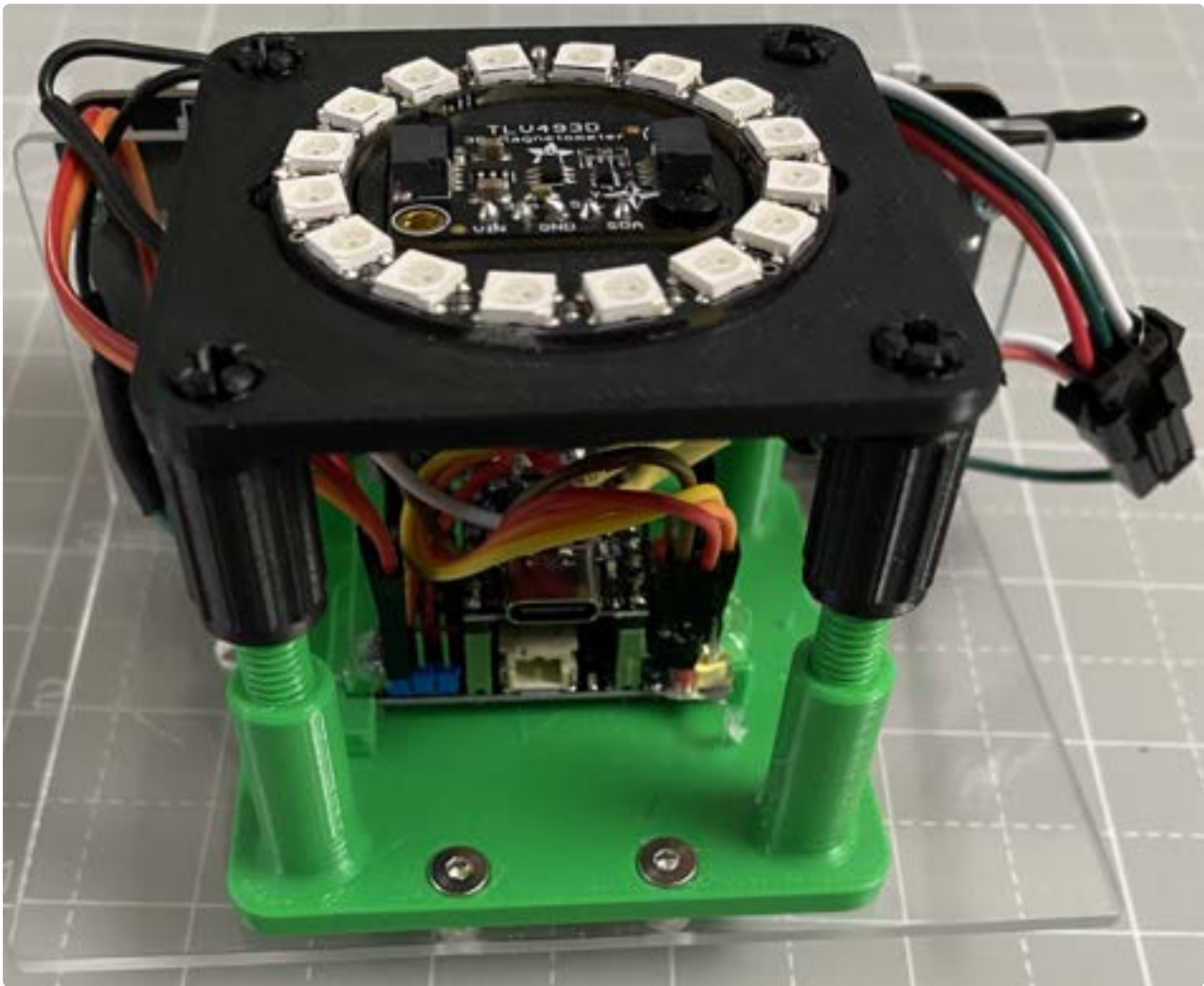
Set the LED ring on the sensor/LED mounting plate. Use hot glue to anchor the LED to the mounting plate. Hot glue can be applied on the bottom side in the holes around the pin headers.



Mount the electronics assembly to the base plate using four M3 × 12mm flat head machine screws and nylon insert lock nuts.

Use hot glue to anchor any Dupont connectors that feel loose.





Assembled Electronics Stack

Testing

A 10mm x 3mm thick neodymium magnet will trigger a 1.5mT threshold at 23mm from the face.
An 18mm x 3mm thick neodymium magnet will trigger a 1.5mT threshold at 39mm from the face.
Magnet orientation (face vs edges) of course matters.
You will need to experiment and choose the magnet.

3.3 Vehicle Operations

3.3.1 Launch/Recovery

Teams are responsible for safely launching and retrieving their vehicle. You may lower and raise your vehicle from the side of the pool at your designated section (A, B, C, D), provided it can be done safely.

The pool is **7 ft (2.1 m) deep**, with a **1 ft (0.3 m) drop** from the pool deck to the water surface.

At each section, a 10 ft (3 m) long pipe with a four-point harness will be provided. Teams will secure their vehicle's hard points to the harness. With two team members, lift the vehicle from its stand, position the vehicle over the water, and lower it into the water. Once in position, a team member can reach down from the edge to unhook the four connections points. To retrieve the vehicle, simply reverse the procedure.

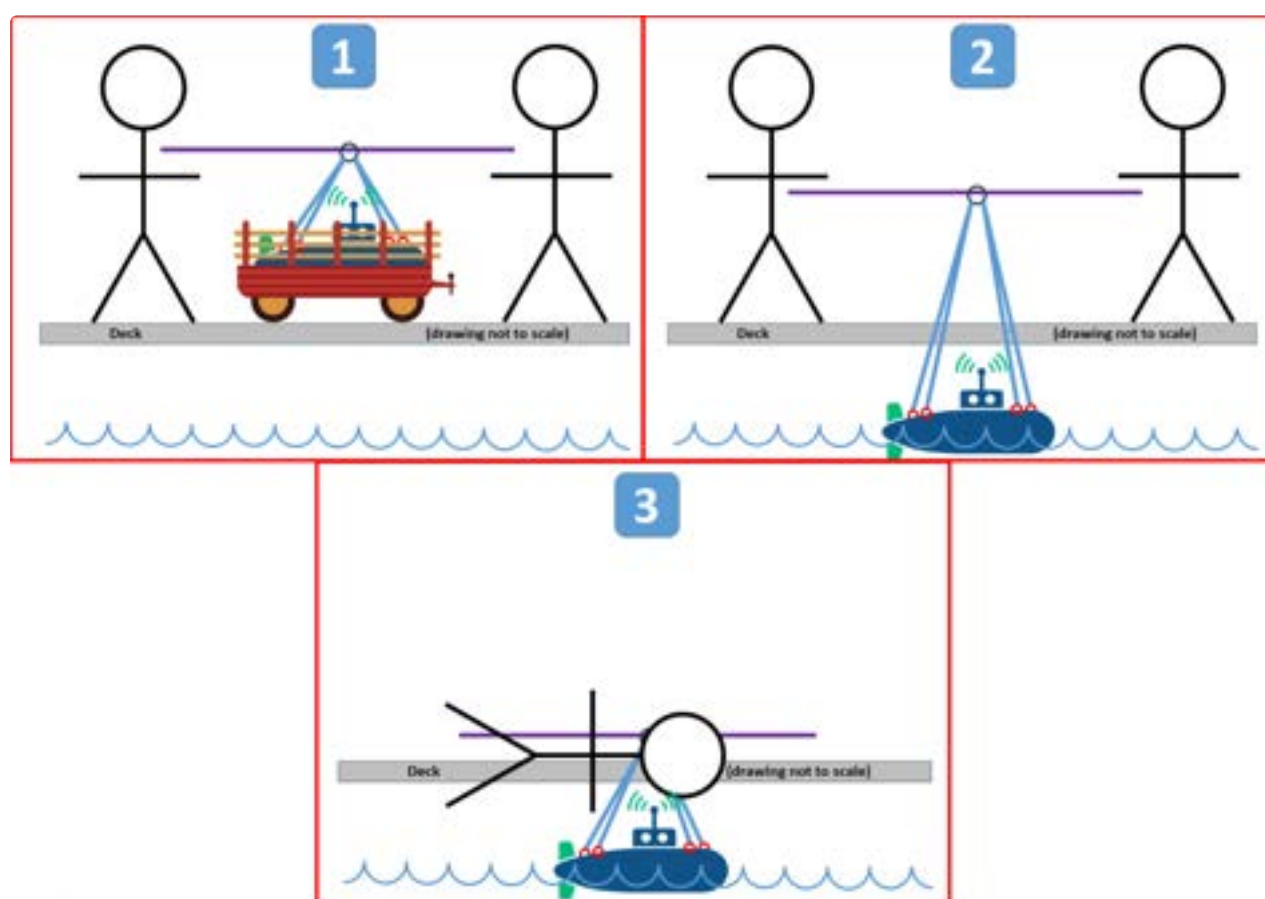


Figure: Raising and lowering the vehicle

For Alpha (A), and Delta (D), we recommend bridging the corner to lower/raise your vehicle. You might want someone in the water for Bravo (B) and Charlie (C) to help keep the vehicle off the wall as the team is lowering/raising the vehicle.



Figure: Location of launch/recovery bars

3.3.2 Harnessing the AUV

For the safety of your vehicle, **all teams are required to use a harness or sling** when launching or retrieving from the water. Even if the vehicle is light enough to hand-carry, a simple slip could result in serious damage — to your vehicle or equipment. Using a hoist is a much safer and more controller method.

In addition, your vehicle may need to be suspended for weighing. It's strongly recommended that you — the builder — integrate sling attachment points into your vehicle's frame during the design process. This is far preferable to us (the competition coordinators) having to improvise a solution on-site at the last minute.

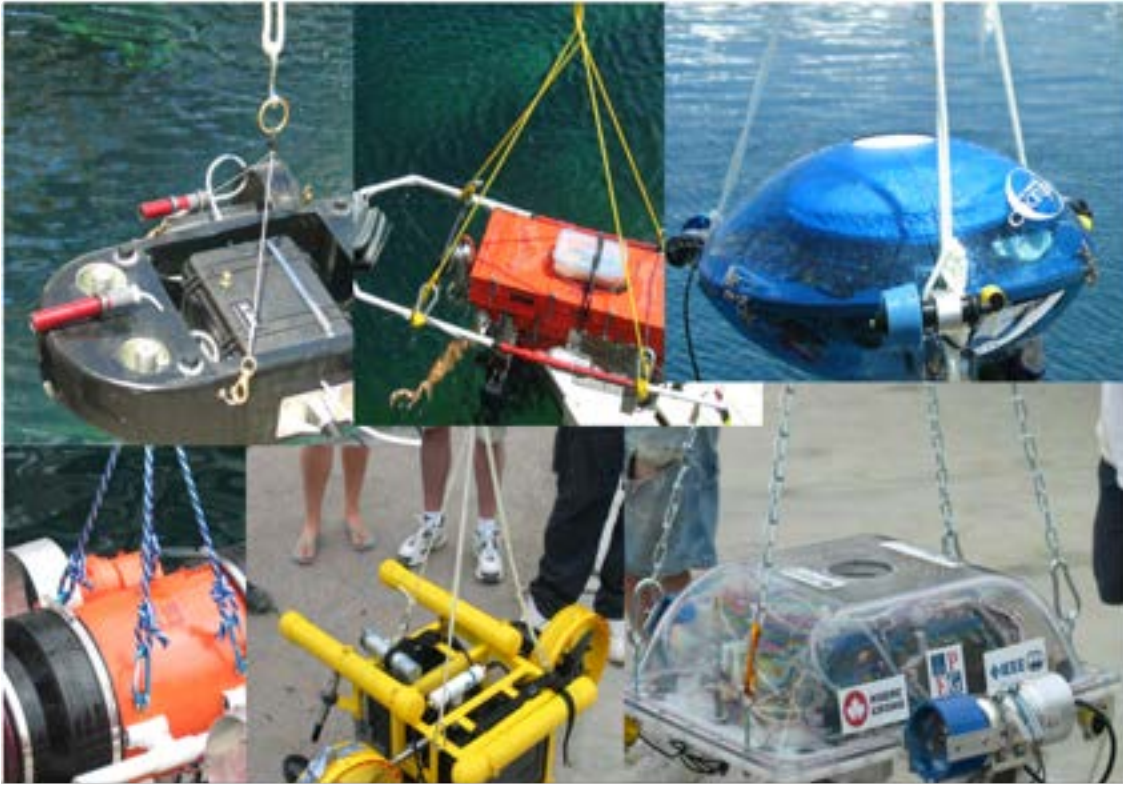


Figure : Examples of harnesses

What to Consider

1. **Hard points on the vehicle.** These are strong, secure attachment points that can support the full weight of your vehicle
2. **Chain, rope, sewn slings**
 - **Chain:** Easy, durable, and ready to go.
 - **Rope:** More flexible, but required good knots.
 - Any knot reduces the breaking strength, but each knot effects the rope differently.
 - **Sewn slings (aka "runners"):** Available at rock climbing stores, REI, or online. Made from materials like Nylon, Spectra, or Dyneema — all plenty strong for this use.
3. **Attachment method:** The easier and quicker it is to attach and detach the harness, the better — especially for people in the water or surface operators.



Figure : Sewn slings (runners)

Recommended Knots for Rope Harnesses

If you're using rope, you'll need to tie proper knots to attach to your vehicle's hard points. Here are the ones worth knowing:

- **Figure 8 Rewoven**
 - Retains ~80% of rope strength
 - Easy to tie and inspect
 - Can be difficult to untie after heaving loading
- **Bowline**
 - Retains ~70% of rope strength
 - Creates a secure loop that's easy to untie, even after loading
 - Great for quick setup, but be cautious of the rope ends
- **Double or Triple Fisherman's (aka Grapevine) Knot**
 - Best for joining two ropes together or creating a permanent loop
 - Very secure and compact.

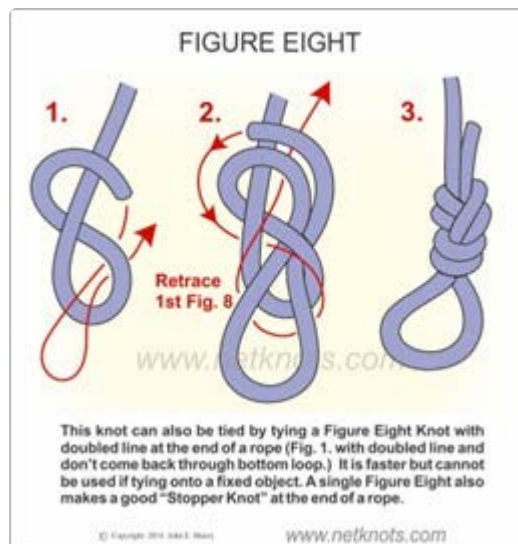


Figure : Figure 8 rewoven knot



Figure : Bowlineknot

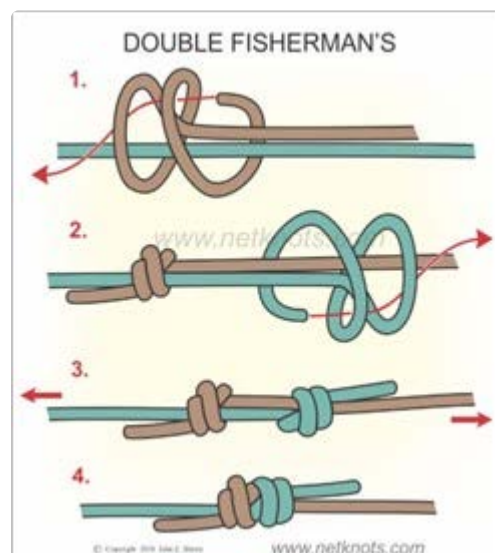


Figure : Double Fisherman's knot

Connecting Everything Together

To attach your harness (chain, rope, or slings) to your vehicle, **use carabiners**. Climbing carabiners like the **Black Diamond Oval** are reliable and inexpensive. You might find alternatives at your local hardware store — but make sure they're rated to handle the full weight of your vehicle, with a safety margin.



Figure : Black Diamond oval carabiner

Final Tip: Keep It Simple

Follow the KISS principle — Keep It Simple, Stupid. Your goal should be a harness system that's:

- Easy to set up and break down
- Quick to attach and detach
- Intuitive enough for someone in the water to operate without hassle.

3.3.3 Team Swimmers

Teams may have an opportunity to volunteer a swimmer(s) on their team to assist with in-water safety and operations. The volunteer swimmer(s) will be required to tread water for 1 minute each time they enter the water (reminder, the whole pool is 7 feet deep!). It is allowed for teams to use another team's swimmer to swim for their run.

For Semi-Finals, Third-Chance, and Finals, no team-provided swimmers will be allowed. Only during Practice/Qualifying runs.

Teams are asked to bring their own swimming equipment (i.e. masks, snorkels, fins, etc.). RoboNation will have a few spare pieces of equipment available for shared use.

3.4 Competition Sequence of Events

This section outlines the sequence of events for the Autonomy Challenge. The competition allows for days of practice, qualifying, semi-final, and finals runs.

3.4.1 OPTIONAL Pre-Qualification Attempt

Prior to the on-site competition, teams may attempt to pre-qualify their vehicle. The vehicle used to pre-qualify must also be the vehicle that is entered into the competition. A team that successfully passes the pre-qualification will automatically qualify for Semi-Finals and is not required to qualify on-site during the practice days of the competition. A team that chooses not to attempt pre-qualification or does not successfully pre-qualify, is required to complete a qualification run on-site (see Qualification Runs below).

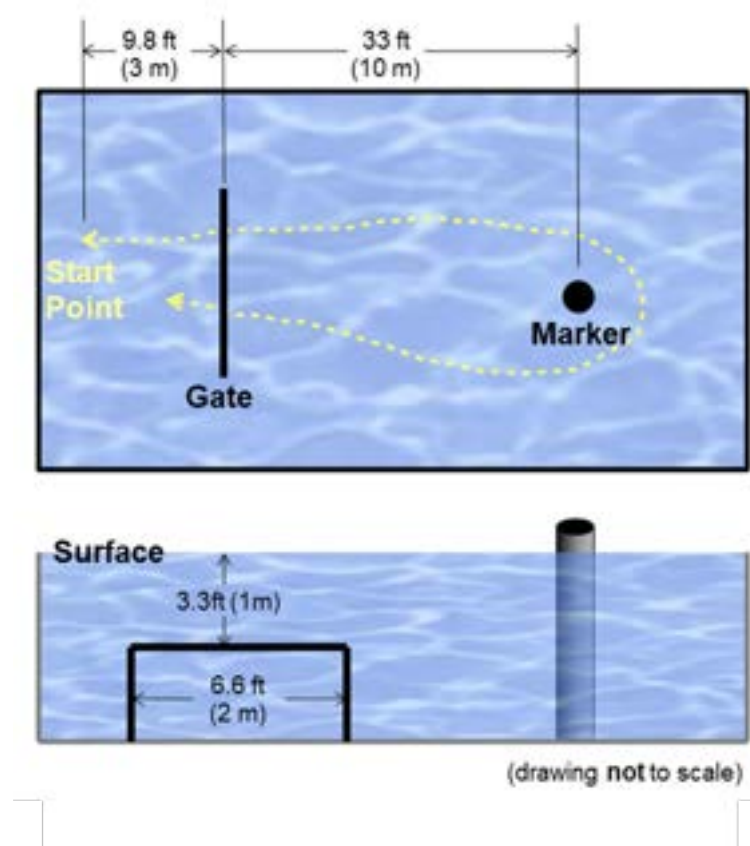


Figure : Pre-Qualification Runs

3.4.1.1 How to Build Pre-Qualification Course

The approved pre-qualification course consists of:

1. horizontal Gate, and

2. vertical Marker.

The **Gate** is 6.6 ft (2 m) in length and is positioned 3.3 ft (1 m) below the surface of the water. The **Gate** can be any diameter and any color the team chooses. The **Gate** can be anchored to the floor by any means necessary (ex. using PVC elbows to create two vertical legs, with a line on each end to moor the **Gate** to the floor, etc.). The vertical **Marker** can be any diameter and any color the team chooses. It must be positioned 33 ft (10 m) beyond the **Gate** and must touch the floor and break the surface of the water.

If a team is unable to build a course to meet these specifications, [notify RoboNation](#)  for alternative instructions to attempt pre-qualification.

3.4.1.2 Pre-Qualification Maneuver

In a fully autonomous run, the vehicle must

- submerge and start 9.8 ft (3m) behind the **Gate**,
- pass through the **Gate**,
- circle around the **Marker**, and
- pass back through the **Gate**.

Everything attached to the vehicle must submerge with the vehicle (nothing floating on the surface). The maneuver is successful if this is all accomplished without breaching the surface. The entire run must be recorded from start to finish with no breaks in the video.

3.4.1.3 Submit Pre-Qualification Attempt Video

Teams can submit pre-qualification video attempts at the following link: robosub.org/pre-qual . This video is submitted to RoboNation for evaluation. Once evaluated, the team is notified of the results. If a team's attempt is denied and the deadline for submissions has not passed, they may submit another attempt.

3.4.2 Practice Runs

Practice time slots are scheduled on an ad-hoc basis by the TD team during the practice days. Teams are provided as much practice time as the venue setup allows. Each vehicle must be approved by the TD team with a mandatory safety inspection before it can enter a practice course. Teams can sign up for one 30-minute practice time-slot at a time. Once their time-slot has completed, the team is permitted to sign up for the next available time-slot for that practice day. During practice days, any course (or partial course) can be used (A, B1, B2, C1, C2, D).



3.4.3 Qualification Runs

To advance in the competition, teams are required to complete a qualification run. On practice days, a team may request that their run be observed as a qualification run anytime during a team's practice run. In order to successfully qualify, the vehicle must pass through the gate autonomously with everything attached to the vehicle submerging with the vehicle.

Qualification allows the team to have two (2) time slots during the semi-finals days, one on the first day and one on the second day. Since there isn't a gate in C2, C2 is the only course where a team can not qualify.

3.4.3.1 Wild Card Slots

For any team that has not qualified during the practice days, wild card slots are available during the semi-finals days. Teams must first qualify (pass through the gate) before they are able to choose the next available wild card slot. Only one slot per day can be used by a non-qualified team.

3.4.4 Semi-Finals Round

There are two semi-finals days. Each qualified team is assigned one time slot on each day to perform the mission. Two of the practice courses are converted into semi-finals courses. Qualified teams are required to conduct a run in each of the two courses across the two semi-finals days. Twenty minutes before the beginning of their time slot, the team may enter the staging area near the launch site. At the beginning of their time slot, the team may move to the launch site. Course A and D are used for semi-final runs. B1, B2, C1, C2 are still available for practice.

3.4.4.1 Semi-Finals Time-slot

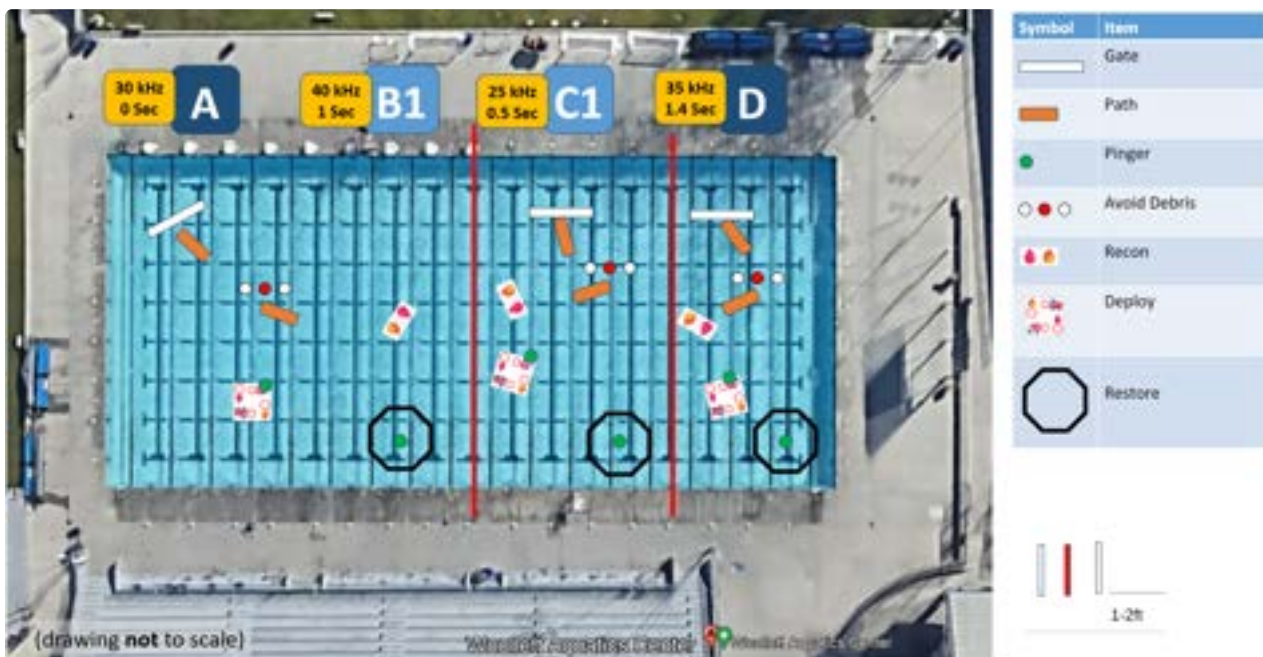
A team will have 20 minutes for their semi-finals time-slot. The first 5 minutes are for preparation (*preparation time*). During this period, the vehicle may not be deployed in the water. When the 5-minute limit has expired for the *preparation time* (or the team has waived the balance of the preparation time), officials begin the *performance time* clock once the vehicle is in the starting position. These competition minutes are for the vehicle to perform the mission. Once this period has begun, the team may ask to have their vehicle placed in the water to begin its run.

3.4.4.2 Vehicle Recovery / End of Run

The run continues until the *performance time* limit has expired, the team lead requests the end of the run, the judges order the termination of the run, or the vehicle breaches the surface. The judges may order termination of the run at their discretion. Once the judges order the end of the run, no further points may be scored. The judges' decisions on the termination of the run are final. As long as a vehicle has passed through the gate, the *performance time* is stopped during the retrieval of the vehicle.

3.4.5 Finals Round

After the semi-finals round, the judges rank-order the teams based on the semi-finals scores and select the top teams to compete in the finals round. The point totals and ranking from the teams not selected for the finals are frozen. For the finals round, all point totals are set to zero. Courses A, B1 and B2 are combined for the finals.



Section 4: Scoring & Awards

This section includes a detailed overview of the competition scoring.

Scores are calculated by the judges' evaluation and observation. All decisions of the judges are final.

[4.1 Design Documentation Scoring](#)

[4.2 Autonomy Challenge Scoring](#)

[4.3 Awards](#)

4.1 Design Documentation Scoring

Design documentation must be submitted in accordance with the requirements outlined in [Section 2: Design Documentation](#) and the deadlines listed in [Section 1.5 Competition Schedule and Timeline](#), to be eligible for full points. After the competition, overall standings for design documentation will be published.

Design Documentation	Maximum Points
Technical Design Report	200
Team Website	180
Team Introduction Video	120
Design Presentation	180
System Assessment	180
Total Potential Points	860

4.2 Autonomy Challenge Scoring

The Autonomy Challenge occurs in three rounds: Qualifying, Semi-Finals, and Finals. Points are awarded only in the Semi-Final and Final Rounds, as outlined in this section. Upon completion of the Semi-Finals Round, the judges will announce the top-scoring teams who will progress to the Finals Round. The judges have the discretion to select the number of teams advancing to the Finals Round.

After the competition, RoboNation will issue Autonomy Challenge overall standings. Any team accepted into the Finals Round will be ranked ahead of all teams that did not participate in the Finals Round.

4.2.1 Point Breakdown

Each task has a point value associated with it. Each vehicle must pass through the gate before attempting any other task. The tasks can be completed in any order by one or more vehicles. The recovered object must be attached to the vehicle when the vehicle is on the surface to obtain maximum points for "surfacing with object".

During a scored timeslot, the team lead may end the run at any time and keep the accumulated points. The team may decide to start another run, in an attempt to accomplish more/different tasks.

Semi-Finals Points – Last Run

For semi-finals, at the start of a new run, the points accumulated from the previous run are forfeited. A new run is started when the vehicle leaves the starting location. The only points recorded are from the very **last** run.

Finals Points – Best Run

For the finals, the **best** run will be used for the final points. Therefore, a team may try to accomplish as many runs as time allows, and the run that has accumulated the most points will be used for their final score. If the minimum requirements have been met, the remaining time after each run will be recorded and used to calculate a time bonus. For example, after the first run, a team has met the time bonus requirements with 10 minutes remaining on the clock. Those 10 minutes are used to calculate the time bonus for that run. Regardless of what happens with the next run.

Task	Maximum Points
Weight	See Table: Weight
Marker / Torpedo exceeding weight or dimensional spec by <10%	-500 / item
Gate: Pass through	100
Gate: Maintain control	150
Gate: Coin Flip	300
Gate: Random Role	150
Gate: Style Yaw, Roll/Pitch	+100, +200 / 90° (8x max)
Avoid Debris: Any, Correct	200, 400 / slalom
Avoid Debris: Correct depth	200 / slalom
Recon: Any bin, Correct bin (one each)	300, 800 / marker (max 2)
Recon: Light interaction	500 / light (max 2)
Deploy: Any, Correct sequence	600 / torpedo (max 2), 1400
Deploy: "Far", "Farther", torpedoes	200, 400 / torpedo
Restore: Surface in Area	800
Restore: Surface facing image any, your role, correct	200, 400, 700
Restore: Surface with object	400 / object
Restore: Drop object	200 / object
Restore: Basket any, correct	500, 700 / object
Restore: Basket count close +-1, correct	500, 1000
Return to Home	300
Random Pinger first task	500
Random Pinger second task	1500
Inter-vehicle Communication	1000
Finish the mission with T minutes (whole + fractional)	Tx100

Pinger Tasks

Deploy and **Restore** will *only* be marked with a pinger. There will be no path markers that point to either task. A team may request that a specific pinger be switched on (pinger near **Deploy**, or pinger near **Restore**). At any time during the run, the team lead may ask to have the pinger switched to the other task. This switch can be done as many times as the team lead asks. Additional points are awarded if the team requests a random pinger.

Random Pinger

If a vehicle can score points at both pinger tasks, the team lead may request a random pinger selection. The only randomization is the selection of the first task(s) marked with a pinger, the second task(s) will always be the other task(s) marked with a pinger. If the vehicle obtains any points from the first task(s), associated with the random pinger, bonus points are awarded. At any time after the vehicle has obtained points from the task(s) associated with the random pinger, the team lead may ask to switch the pinger. If the vehicle obtains any points from the second task(s), associated with the random pinger, bonus points are awarded.

If the team lead requests to switch the pinger before the vehicle has acquired any points, the run reverts back to a specific pinger request run and no random pinger points will be awarded.

Breaching

When completing a sequence of tasks, a team may choose to complete the surfacing task (surface within the floating area) at any time. A vehicle may breach the surface within the floating area and then submerge again to compete the remaining tasks without the risk of ending the run. For a vehicle to continue after breaching, it must surface within the floating area, and may be touching the surfacing task. A breach outside of the floating area will end the run of that vehicle. If there are multiple vehicles underway (and underwater) this does not end their run. The remaining vehicles may continue their own autonomous mission and continue to score points for their run. If the breached vehicle cannot be removed safely without interfering with the remaining vehicle(s), it will be allowed to continue its run, but will not score any more points for that run.

Interference

Vehicles that interfere with competition elements may be disqualified at the judges' discretion. "Interference" does not include cases where, in the opinion of the judges, a vehicle is attempting to complete one of the tasks. If a vehicle becomes entangled on a competition element the run will be declared complete. Teams may keep the points earned on that run or may have the vehicle returned to the dock and start another run. If a new run is begun, all points from the previous run are forfeit.

Passing through the gate: The judges' discretion will determine whether or not the vehicle satisfactorily passes through the gate. To get maximum points, vehicles need to pass through the gate cleanly (don't touch either of the side, touching the divider or images is ok).

Maintain control through the gate: Was the vehicle in control as it passed through the validation gate? This is intended to distinguish between vehicles demonstrating autonomous control versus those relying on manual compensation for hardware or tuning issues.

For example:

- A vehicle with slight side-to-side (sinusoidal) movement due to PID tuning, but that generally maintains its heading, **is considered to be in control**.
- A vehicle that searches for the gate, identifies it, and then proceeds through it intentionally, **has also maintained control**.

In contrast:

- A vehicle that is **intentionally aimed away from the gate** to counteract drift from unbalanced motors or poor tuning — then **drifts through** the gate — **has not maintained control**.

This evaluation is about whether the vehicle is actively navigating, adjusting, or holding a heading on it's own, not just passively ending up in the right place.

Surface within the Area: The vehicle must fully surface within the floating area to obtain max points. Partial points will be awarded based on how much the vehicle is inside the area.

Grabbing the Object: The object must be captured and constrained by the vehicle to obtain full points. Partial points may be awarded for a partial capture (i.e. a hook/magnet).

Releasing the Object: The object must fall free from the vehicle to obtain full points. An object hanging on the vehicle may be awarded partial points with judges' discretion.

Inter-vehicle Communication (IVC): Teams may enter up to two vehicles into the competition for simultaneous operation. The level of the *communication* and *collaboration* demonstrated by the AUVs will determine the level of points awarded. Proof of the communication must be presented to the judges to evaluate. Having indicator lights which draw attention when they are transmitting and receiving IVC messages would help with the confirmation (but are not required).

- **Simple (1-33% points)**
 - One-way communication or rudimentary acknowledgement after log review.
 - Sub 1: Signals mission state (ex. Flash green, task complete).

- Sub 2: Detects signal and initiates a predefined action (ex. Flash green, surface)
- **Intermediate (34-66% points)**
 - One-way communication without log review or rudimentary Two-way acknowledgement after log review (34-66% points)
 - Sub 1: Signals mission state (ex. Flash green, task complete).
 - Sub 2: Acknowledges receipt (ex. Flash green, start a task).
 - Sub 1: Confirms acknowledgement (ex. Flash green).
- **Complex (67-100% points)**
 - Two-way acknowledgement without log review to two-way exchange that results in modified vehicle behavior.
 - Sub 1: Signals location (ex. Flash green, at Torpedoes)
 - Sub 2: Acknowledges receipt (ex. Flash green, ready and waiting)
 - Sub 1: Completes tasks, initiates modified behavior (ex. Flash orange, missed, you try at Torpedoes)
 - Sub 2: Completes current task and heads to Sub 1 task (ex. Flash orange, move to Torpedoes, try to score points).

Time Bonus: At a minimum, a vehicle must pass through one row on Slalom, drop at least one marker in a bin (or fire one torpedo through the opening), and fully surface within the floating structure to obtain a time bonus. These tasks can be completed in any order.

The time bonus is a calculation of whole minutes remaining plus fractional seconds. For example, with a remaining time of 7:13, a team will receive: $(7+13/60)*100 = 721.667$ points (approximately).

Additional Scoring Considerations

1. There is a 10 ft (3 m) radius imaginary buffer (spherical) around each task. When a vehicle enters the buffer, an attempt for that task has started. When a vehicle exits the buffer the attempt for that task has ended.
2. If multiple tasks are grouped such that there isn't the required separation, the attempt on the first task has ended when the vehicle has clearly moved on to the next task.
3. If a task is a single event (pass through the gate, touch buoys, etc.), points for a task are awarded on a per attempt basis.
4. If a task can collect items (i.e. it has a bin), points are added until the maximum points are reached. I.e. If there is a maximum of two markers in a bin, one vehicle drops 1 marker in the bin, and a second vehicle drops 2 markers in the bin, the points are capped at 2 markers in the bin.

5. The higher value for a task during a run replaces the previous score. If a vehicle revisits a task in the same run, the higher score is used.
6. Semi-Finals Round: Each vehicle is scored independently, the run starts when the vehicle leaves the starting location and ends when the team lead calls to kill that vehicle, the vehicle breaches, or the time runs out. The scores are based on the last run of each vehicle.
7. Finals Round: The "Best of" run for each vehicle is used to determine the final score.

4.3 Awards

Awards are provided in three categories: Autonomy Challenge standings, Design Documentation standings, and Special Awards. Teams must be present to collect their awards, and award money will be issued within 4-6 weeks after the competition.

4.3.1 Autonomy Challenge Ranking

Teams are awarded prize money reflective of their autonomy challenge ranking after scores are calculated. The first-place teams receive a RoboNation champion banner.

4.3.2 Design Documentation Ranking

Teams are awarded prize money reflective of their design documentation ranking after scores are calculated.

4.3.3 Special Awards

Throughout the competition, teams, judges, and staff are asked to be on the lookout for exemplary behavior from teams to acknowledge with special awards. Nominations are collected at the following link, until the day before finals: robosub.org/award-nomination ↗.

Section 5: Rules & Requirements

This section includes the rules governing the competition, safety and vehicle requirements and specifications related to the competition.

[5.1 Rules](#)

[5.2 Safety Requirements](#)

[5.3 Vehicle Requirements](#)

[5.4 Competition Specifications](#)

5.1 Rules

1. **Code of Conduct:** All team members must abide by the RoboNation Code of Conduct while participating in the Competition. Failure to abide by this Code of Conduct at any point during the competition season may result in the disqualification of the team and/or participants from the Competition, components of the competition, the full competition, and/or future competitions. ([Section 1.6: RoboNation Code of Conduct](#))
2. **Vehicle Entry:** Teams must build an AUV to compete and enter up to two vehicles in the competition. ([Section 5.3 Vehicle Requirements](#))
 - a. **Rookie Teams:** First-year teams are eligible to participate in RoboSub without an AUV. These teams are expected to participate in Design Documentation and send representation on-site at the event as a learning experience. First-year teams must indicate this option in their registration form.
3. **Vehicle Requirements:** Teams that arrive at the competition failing to meet the vehicle requirements will not be permitted on the course, until the vehicle is modified to meet all requirements. ([Section 5.3 Vehicle Requirements](#))
4. **AUV Safety:** Prior to entering the Autonomy Challenge courses, teams must demonstrate the ability to operate their AUV safely. ([Section 5.2 Safety Requirements](#))
5. **Team Composition:** Teams must be comprised of 75% or more full-time students. ([Section 1.3 Eligibility](#))
 - a. **Team Lead:** One student member of the team must be designated as the “team lead”. The team lead must be conversationally fluent in English. The team lead, and only the team lead, will speak for the team during competition runs.
6. **Attendance:** Teams must have at least one representative present onsite at the competition venue during the competition hours (7:30 am – 6:00 pm) to be eligible for prizes. If teams cannot be onsite, they must notify RoboNation staff in a timely manner.
 - a. **Orientation Attendance:** Teams must have at least one representative present for the team orientation. Teams who miss orientation will not be permitted to deploy their AUV.
7. **Potential Damage:** RoboNation is not responsible for any damage to a team’s AUV as a consequence of participating in the competition.
8. **Competition Suspended:** The officials may suspend the competition at any time they deem that it is required (i.e. for safety or security reasons).
9. **Award Money:** Only the student component of each team is eligible for award money.
10. **Judge Decisions:** All decisions of the judges are final. ([Section 4: Scoring & Awards](#))

11. **Course Entry:** Unless otherwise specified, no team member is allowed to enter the course at any time (this includes wading, swimming and diving as well as floats, boats, etc.) Competition officials are responsible for recovering lost vehicles. Officials make all reasonable efforts to recover a lost vehicle but cannot guarantee that they will be able to do so. All teams recognize that by entering the competition, they risk damage to or the loss of their vehicle. The judges, officials, hosts, and sponsors can take no responsibility for such damage or loss.
12. **Retrieving Vehicle:** At any time, the team lead may signal the end of the run and request the retrieval of the vehicle. Only officials may retrieve a vehicle and return it to the dock. The countdown clock for the semi-final performance period stops when the official touches the vehicle and continues its countdown once the vehicle is safely back at the starting location, or the team establishes communication with the vehicle, whichever is first (i.e. if a team has wireless communication with the vehicle, the countdown clock continues while the official returns the vehicle to the start).
13. **Interference:** If a vehicle experiences significant interference from a piece of equipment, line, cable or official deployed in support of the competition, the team lead may ask, at that time, to have the clock stopped, the vehicle returned to the dock, and for the judges to add back to the clock their best estimate of the time used in that run up to the point of interference. If the team lead does not make this request in a timely manner (as determined by the technical director) then the option is lost. Interfering with the competition tasks does not qualify for this option, and a vehicle interfering with tasks may be disqualified at the judges' discretion.
14. **Lock Score:** After a run, a team may lock in their current score and use any remaining time to survey the arena. The survey must be completed autonomously. Unlike performing a competition run, the clock will continue to run while retrieving a vehicle. This is subject to change depending on timing and the number of teams.
15. **Mission End:** The run ends when any of the following occurs:
- The performance period time limit ends;
 - The judges' order the end of the run;
 - The team lead requests the end of the run; or
 - The vehicle breaches the surface outside the octagon.

5.2 Safety Requirements

Safe operations are a priority for RoboNation. All considerations to maintain safety for operators and the surrounding environment must be made. These guidelines are the minimum requirements for all participants and their systems during the competition.

1. All Radio Frequency (RF) equipment must be operated within the rules and regulations of the host country. This includes, but is not limited to, frequency, transmitting power, antenna height, etc.
2. AUV power systems must follow the safety rules and regulations of the host country as well as the team's home country.
3. RoboSub staff may suspend team operations at any time for safety or security considerations. The staff is not required to advise the team prior to the decision to terminate the run attempt. In all matters of safety, the decisions of the RoboSub staff are final.

5.2.1 Safety Inspections

Before operating in the water, all systems must pass a safety inspection. This includes, but is not limited to:

1. Clear identification of kill switch and verification of operation.
2. Shrouded propellers.
3. Components safely secured on the vehicle (that should remain in the vehicle).
4. Safe areas identified for the diver to grab/secure the vehicle.

5.2.2 Battery Safety Requirements

Teams are required to understand and follow battery safety best practices on the battery chemistry selected by the team. Lithium-ion chemistry batteries may become damaged and create a hazard if misused/abused, representing the greatest risk to people, facilities, and the environment. The following safety rules and requirements must be followed:

1. Teams must submit battery specifications, Material Safety Data Sheets (MSDS), and proper disposal procedures, sourced from the battery manufacturer for all batteries.
2. Teams must keep a hard copy of the battery safety documentation for all batteries in Team Village (on-site) at all times, for reference.
3. Teams must bring a LiPo safe bag(s) adequate for the lithium batteries used. LiPo bag(s) must be available at the competition and the hotel.

4. Li-Po (Lithium Polymer) battery packs need cell level safety and balancing circuits and must be labeled HAZMAT when shipped.
5. Each team must understand and follow their own country's regulations as well as those of the host nation.
6. All batteries must be stored, used, and maintained in accordance with manufacturer guidelines.
7. Teams are required to inspect their batteries daily for signs of swelling, heat, leaking, venting, burning or any other irregularities.
 - a. Lithium batteries that become too warm during use or have become swollen or malformed must be removed from use and reported to RoboNation.
 - b. Lithium batteries that do not hold a charge must be removed from use and reported to RoboNation.
8. A team member must be present at all times to monitor charging batteries.
9. At the competition site, if any of the above battery conditions are observed students must immediately notify RoboNation and provide the battery specifications and safety information.
10. At the hotel, if a battery irregularity occurs at any time, students must notify RoboNation's Senior Events Manager, Cheri Koch immediately by phone at 850.642.0536 and provide the battery specifications and safety information.
11. Failed or failing Lithium-ion batteries must be handled in accordance with manufacturer's safety and disposal guidelines. In the absence of specific guidelines, batteries must be placed in a LiPo safe bag, which must then be placed in a bucket, covered with sand, and placed in a designated safety zone.
12. Teams are only permitted to change or replace AUV batteries in their designated areas in Team Village.

5.3 Vehicle Requirements

The following is a list of minimal requirements for a vehicle to be permitted access to a course.

Teams that arrive at the competition failing to meet the vehicle requirements will not be permitted on the course until the vehicle is modified to meet all requirements.

5.3.1 AUV Requirements

- **Inspection:** Each team may enter one or two vehicles into the competition. Each vehicle is physically inspected by the TD team. The TD team may disqualify any vehicle that they deem to pose an unreasonable safety hazard to participants, staff, or the host facility. The sponsors and the host organization, their employees and agents, as well as the organizing committee, are in no way liable for any injury or damage caused to or by any vehicle.
- **Autonomy:** Vehicles shall be fully autonomous and shall have all autonomy decisions made onboard the AUV. During qualifying, semi-finals, or finals run, each vehicle must operate autonomously. While carrying out the run, no communication is permitted between the vehicle and any person or off-board computer. Each vehicle must operate solely on its ability to sense and maneuver in the arena using on-board resources. Autonomy is not necessary for practice runs.
- **Submerge:** When performing a qualifying, semi-finals or finals run, everything attached to the vehicle must be submerged with the vehicle. Any part that breaks the surface is considered a breach. During practice days, and practice runs, the vehicle and buoys may be used on the surface for communication.
- **Weight and Size:** The weight of each individual vehicle must be less than the maximum allowed. Note that bonus points are awarded to vehicles below a certain weight, and penalties assessed for those that exceed it, see Table 3. The entire vehicle must fit within a 3ft x 3ft x 6ft (0.9m x 0.9m x 1.8m) volume.
- **Batteries:** Vehicles must be battery powered. All batteries must be sealed to reduce the hazard from acid or caustic electrolytes. Batteries must not be charged inside of sealed vessels at any time. The open circuit voltage of any battery (or battery system) in a vehicle may not exceed 60 VDC. If a team has any questions or concerns, they are encouraged to contact the Technical Director Discord's RoboSub Channel. ([Section 5.2.2 Battery Safety Requirements](#))
- **Markers:** No materials (except for the markers/torpedoes and compressed air) may be released by the vehicle into the waters of the arena. ([Section 5.4.1 Markers](#))
- **Torpedoes:** For the safety of your team and those around you, no loaded torpedoes are allowed within the team tent. If you must test your launchers, tests may be conducted either in the water or in an open area pointing away from everyone and everything. ([Section 5.4.2 Torpedoes](#))

- **Harness:** When a hoist or crane is used, vehicles are required to be slung on a harness or sling of some type. Even if the vehicle is light enough to hand carry, this requirement is in place to avoid harm to the vehicle. The harness/sling is used to weigh the vehicle and launch/recover. Since the diver in the water will be responsible for removing and placing the harness on the vehicle, make sure this is as easy as possible to do.
- **Kill Switch:** All vehicles must contain a clearly marked kill switch that a diver can easily and readily activate. The switch must disconnect the batteries from all propulsion components and devices on the AUV. Note, this does not have to kill the computer. Upon reactivation, the vehicle must return to a safe state (props do not start spinning). Vehicles will not be allowed in the water without a properly working kill switch.
- **Shrouded:** All props must have shrouds. The shrouds must surround the prop and have at least a 2" (5.1cm) distance between the spinning disk of the prop and the edges of the shroud (front and back). If you have a guard across the opening to prevent the insertion of a finger, this distance can be minimal. Commercial shrouded thrusters can be used as is. Vehicles will not be allowed in the water without prop shrouds.
- **Buoyancy:** All vehicles must be positively buoyant by at least one half of one percent (0.5%) of their mass when they have been shut off via the kill switch.
- **Suspension:** The officials will suspend the operation of a vehicle at any time they deem that it is required by safety or security considerations. If teams have any questions or concerns, they should submit technical descriptions of their vehicle to the officials in advance of the competition, with the goal of identifying potential safety concerns well in advance. Such technical information submitted to the officials will be held in confidence until the end of the competition.

5.3.2 Multiple Vehicle Requirements

Up to two vehicles per team are allowed in the competition. Along with the [5.3.1 AUV Requirements](#), teams who enter multiple vehicles must follow these specifications as outlines in [5.3.2 Multiple Vehicle Requirements](#):

- **Volume:** The total dry volume for all the vehicles must fit within the maximum volume defined in the requirements. The vehicles are not required to start joined together, nor are they required to rejoin at the end of the run.
- **Weight and Size:** Each vehicle is weighed, and the bonuses/penalties are calculated on a per vehicle basis (Table 3: Vehicle weight in air with Bonus or Penalties).
- **Gate:** From the dock, each vehicle must pass through the validation gate first before heading off for its desired task.
- **Run Time:** A team may elect to kill one vehicle and bring it back to the dock. If one (or more) vehicles are still out on the course, the competition time continues to count down (think of them as a swarm). Any vehicle that has been killed or has breached are returned to the dock and can be redeployed at any time.

- **Time Stop:** The competition timer is only stopped when the last vehicle out on the course is under diver control and returning to the dock. The timer starts again once this last vehicle has returned to the dock, or the first vehicle leaves the dock (starting its new run).
- **Inter-Vehicle Communication:** Teams wishing to have communication between each vehicle must post their method and frequencies on the [RoboSub Discord's technical-forum](#) ➤ channel. Acoustic frequencies that are the frequency range used by the pingers, are always off limits for inter-sub communication. Inter-vehicle communication and cueing of one vehicle by another is an advanced behavior that merits special points. If such behavior is executed, teams are required to present post-run supporting documentation (e.g., vehicle logs) to the judges.

5.4 Competition Specifications

5.4.1 Markers

- Each marker must fit within a box 2.0" square and 6" long (51 × 51 × 152 mm).
- Each marker must weigh no more than 2.0 lbs (0.91 kg) in air. Any marker that exceeds these limits by less than 10% results in a 500-point penalty. Any marker that exceeds these limits by more than 10% is disqualified.
- Each marker must bear the team's name, a color or emblem.
- Markers are cleared from the arena after each run.
- A vehicle may carry up to two markers.
- It is recommended to bring backup markers in case of lost markers.

5.4.2 Torpedoes

The torpedo size, weight, and marking requirements are the same as the Markers.

- Each torpedo must fit within a box 2.0" square and 6" long (51 × 51 × 152 mm).
- Each torpedo must weigh no more than 2.0 lbs (0.91 kg) in air. Any torpedo that exceeds these limits by less than 10% results in a 500-point penalty. Any marker that exceeds these limits by more than 10% is disqualified.
- Each torpedo must bear the team's name, a color or emblem.
- Torpedoes must travel at a "safe" speed. A "safe" speed is one that would not cause a bruise when it strikes a person underwater from close range.
- Torpedoes are cleared from the arena after each run.
- A vehicle may carry up to two torpedoes.
- It is recommended to bring backup torpedoes in case of lost torpedoes.

5.4.3 Pingers

The pinger model selected for use is the Benthos ALP-365. The Benthos ALP-365 is user selectable from 25 to 40 kHz in 0.5 kHz increments. It also has multiple options for repetition rate.

Pinger specifications can be found at: robonation.org/benthos-locator ↗.

NOTE: These pingers are no longer in production and are unavailable for purchase. RoboNation is working to replace the pinger system in future competition years.



Pingers are activated as described in the applicable task descriptions. The frequency and pulse rate of the pingers in each field may change daily; this information will be made available to teams on site. The full range of frequencies (25 – 40 kHz) and pulse rate (0.5 Hz to 2 Hz) can be used throughout the competition.

During the competition there are multiple units active at any time, with at least one in each course. To mitigate interference issues, each active pinger is separated by at least 2 kHz in frequency. The pingers are also controlled such that they send out a pulse at time intervals in sequence with the other courses.

For example, the two pingers in section A both have the same frequency, and the two pingers in section B both have the same frequency (but different from section A). There are four different frequencies used, one for each section, and only one pinger in each section is active at a time. The ping for each section is deconflicted with the pings in other sections such that only one pinger pings at a time. The frequencies for the sections are:

- A – 30kHz
- B – 40kHz

- C – 25kHz
- D – 35kHz

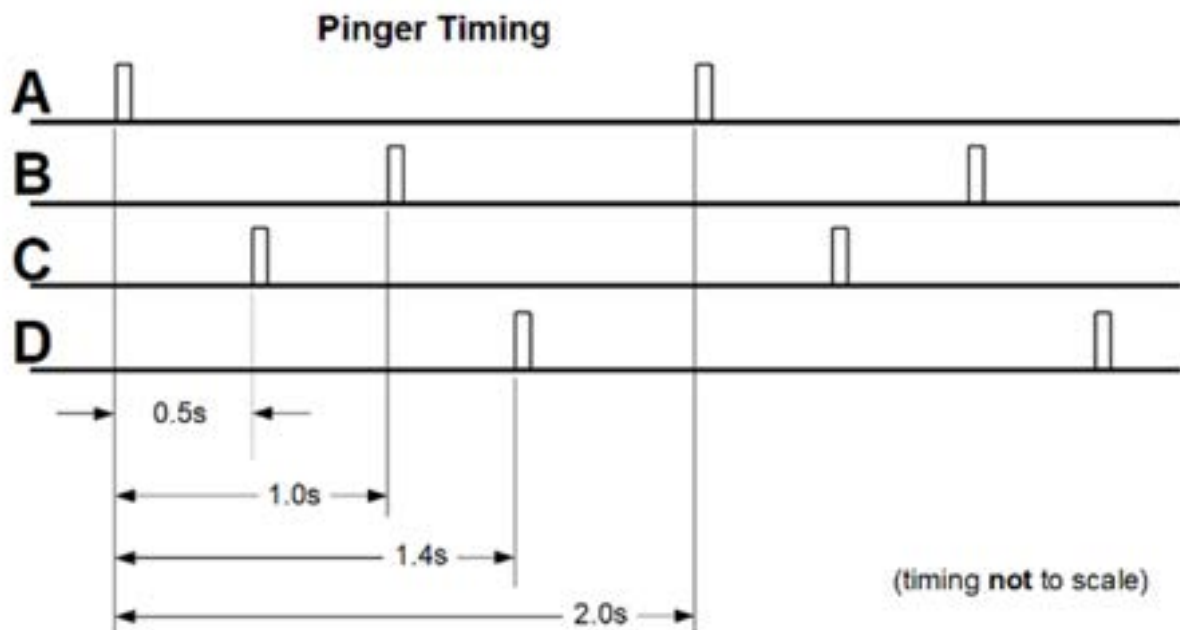


Figure : Pinger timer for the four sections

Section 6: How to Compete

This section includes detailed instructions and requirements that are required to register and participate in the competition.

[6.1 Registration](#)

[6.2 Event Submissions](#)

[6.3 Design Documentation Submissions](#)

[6.4 Event Expectations](#)

[6.5 Team Communications](#)

[6.6 Data Sharing](#)

6.1 Registration

All teams are required to register to compete using the Registration form found on the RoboSub website, RoboSub.org/2026 ↗. This registration collects each team's point of contact information, demographics, and the Pre-Competition Requirements outlined in [Section 6.2: Event Submissions](#) and [Section 6.3: Design Documentation Submissions](#).

6.1.1 Registration Fees

To complete the RoboSub 2026 registration, teams must pay the registration fee of **\$1,500 USD**.

6.1.2 Cancellation and Refund Policy

To cancel a registration, teams must complete the [Cancellation Form](#) ↗. Cancellation requests submitted via email will not be accepted. Click here to review the cancellation and refund policy: robosub.org/cancellation-policy ↗.

6.1.3 First-Year Teams

First-year teams are eligible to participate in the competition without a vehicle. These teams are expected to participate in Design Documentation and send representation on-site at the event as a learning experience. First-year teams are expected to indicate this option in their registration form.

6.2 Event Submissions

This information is collected prior to participation on-site at the competition, during the registration process.

6.2.1 Team Member Registration

This form is required for all team members, advisors, and chaperones planning to attend the competition on-site. Each individual will be able to enter and submit their own information using this process. This information includes name, contact information, dietary restrictions, academic information, optional resume, emergency contact information, signed forms, and a request for an invitation letter.

- Download the [waiver](#) (required of all minor and adult participants)
- Download the [youth protection policy form](#) (required of all adult participants, over the age of 18 years)

 The registration owner will need to collect an email address for each team member to send the team member registration form. For team members that are minors, please enter the email of a parent or guardian to complete the form.

The registration owner is responsible for following up with each team member to complete this task before the deadline.

6.2.2 Team Demographics

Team demographics are collected to determine program impact on students and in educational settings. This information may also be shared with any eligible sponsors.

6.2.3 Merchandise Order

Using the RoboSub Competition Shop, teams place an order for their team's shirts. A discount code is provided in the registration portal to receive the first five t-shirts for free. Additional shirts cost \$15 each.

6.2.4 Vehicle Information

This submission documents a list of all components utilized in the system design. In cases where components were developed by the team versus purchased off the shelf, this information should be included. Additionally, if commercial off the shelf equipment were significantly modified this should be noted. Under the column marked "Specs" a web link to the manufacturer's specifications may be provided. This standardized table will help document and track trends in component (hardware and software) usage and team metrics.

	Vendor	Model/Type	Specs	Custom/ Purchased	Cost	Year Purc
Buoyancy Control						
Frame						
Waterproof Housing						
Waterproof Connectors						
Thrusters						
Motor Controls						
High Level Control						
Actuators						
Propellers						
Battery						
Converter						
Regulator						
CPU						
Internal Comm Network						
External Comm Interface						
Compass						
Inertial Measuremen t Unit (IMU)						
Doppler Velocity Logger (DVL)						
Manipulator						

Algorithms						
Vision						
Acoustics						
Localization & Mapping						
Autonomy						
Open-Source Software						
Inter-Vehicle Communication						
Programming Language(s)						

6.2.5 On-Site Requirements

Battery Safety Requirements

Teams are required to submit battery specifications, Material Safety Data Sheets (MSDS), and proper disposal procedures, sourced from the battery manufacturer for all batteries. More information can be found in [Section 5.2: Safety](#).

Shipping Plan

Teams are required to submit a shipping plan to facilitate shipment receipt/handling at the competition hotel. Shipping guidelines can be found in Section 6.4.2: Shipping. This shipping plan must include:

1. Organization name
2. Team name
3. Shipping POC
4. Shipping POC mobile number
5. Shipping POC email address
6. Number of crates

7. Dimensions for each crate
8. Estimated shipping date
9. Shipping Company
10. Type of shipment – Air, ground, ocean
11. Has initial pick-up or drop off been scheduled – include date of pick-up or drop off
12. Is this a dangerous good shipment? If so, has a dangerous goods shipment been arranged?
13. Have you scheduled your outbound shipment pick-up or drop off? Provide pick-up details (date/time) for any pick-up from the hotel.
14. Additional information for shipment, if needed.

6.3 Design Documentation Submissions

This information is collected prior to participation on-site at the competition, during the registration process. Submission requirements, guidelines, and scoring rubrics can be found in [Section 2: Design Documentation](#).

Design Documentation submissions collected before the competition include:

- [Technical Design Report](#)
- [Team Website](#)
- [Team Introduction Video](#)

6.3.1 Optional Community & Outreach

Teams are invited to outline their educational outreach efforts. This activity is not scored; however, it will be shared online for the community and can be eligible for special awards and recognition. Teams may submit a description (500 word limit) of their activities and any supporting documents.

6.4 Event Expectations

6.4.1 Travel + Lodging

Teams are responsible for coordinating their own lodging and travel plans.

Lodging—Event Hotel

RoboNation has contracted with a local hotel to provide a special rate for RoboSub teams.

Teams are responsible for booking their own lodging for the event. Once available, the booking information can be found on the [RoboSub website](#) ↗.

Travel Considerations

VISA Process – It is recommended for international students to acquire a B-1 Visitor VISA to attend the competition. However, if the student has plans for any other activities besides the competition, they may choose to investigate other types of visas. Explore the different types of visas: travel.state.gov ↗.

Invitation Letter – Once a team is officially registered and the registration fee is paid, they are eligible to request invitation letters. During the [Team Member Registration](#), each team member are given the opportunity to request an invitation letter issued by RoboNation. Contact support@robonation.org ✉ with any questions.

6.4.2 Shipping

Teams are responsible for coordinating the necessary shipping to ensure arrival of AUV and equipment. Any shipping questions can be directed to Cheri Koch at ckoch@robonation.org ✉ / 850.642.0536.

- **Optional Shipping Location:** Teams may ship their equipment to the event hotel (Hilton Irvine / Orange County Airport).
- **Equipment Arrival:** Shipments should arrive no earlier than Saturday, July 4. Shipments must be picked up at the event hotel by Saturday, July 11.

- **Equipment Outbound Pick-Up:** Shipments must be shipped back no later than Saturday, July 18. Outbound shipping must be picked up BEFORE the team departs to return home. RoboNation and the competition venue staff are not responsible for ensuring that team's outbound shipment gets picked up.

Inbound Shipping

Shipments cannot arrive prior to Saturday, July 4. The hotel does have a loading dock to facilitate your large containers. Schedule deliveries during weekday business hours so that management staff will be on-site to direct the shipment. Please provide the hotel's direct phone number to the shipping company so that they can call with questions. Hilton Irvine / Orange County Airport - +1-949-833-9999.

Shipping to the Competition – Shipments should be sent to the hotel using the applicable shipping label below.

Outbound Shipping

 **Begin working on your outbound shipping arrangements now! Batteries are exceptionally difficult to ship.**

Shipment must be picked up no later than Saturday, July 18. Shipments remaining after August 18 will incur a storage fee.

Shipment must be picked up from the hotel BEFORE the team departs or shipments must be dropped off at a local shipping facility. All shipments must be pre-paid - NO EXCEPTIONS.

Local Shipping Outlets:

FedEx Ship Center (4 mi away)

Accepts Dangerous Goods

7000 Barrance Parkway, Irvine, CA 92618

800-463-3339

FedEx Office Print & Ship Center (5.7 mi away)

4187 Campus Drive, Suite M170, Irvine, CA 92612

949-854-7557, USA0590@FEDEX.COM

The UPS Store - Heritage Plaza (0.7 mi away)

14252 Culver Drive, Irvine, CA 92604

949-559-9007, Store0032@theupsstore.com

Hazardous Shipping: LiPO Batteries

- FedEx Dangerous Goods: dghotline@fedex.com, 1-800-463-3339 x81

A pick-up for a dangerous goods shipment can also be coordinated through FedEx. Team must create a label and arrange a dangerous goods pick-up. The team must ensure that a team member is present until the shipment is picked up. This must be done Monday – Friday 9:00 am – 5:00 pm. It will be very difficult if not impossible to schedule this pick-up on the weekend, so make arrangements early!!! The best way to get this shipment on its way is to drop it off at the FedEx Ship Center that accepts this type of shipment.

Shipping Labels

FROM: School/Team Name	
Address	
City, State, Zip	
Country	
 Hilton Irvine/Orange County Airport	
Attn: RoboSub / School Name – Guest Name	
18800 MacArthur Blvd.	
Irvine, CA, USA 92612	
On-site Team POC Name:	Phone:

Inbound Shipping Label (to competition)

FROM: School/Team Name 18800 MacArthur Blvd. Irvine, CA, USA 92612		
School/Team Name c/o School POC Address City, State, Zip Country		
Team POC Name:	Phone:	

Outbound Shipping Label (after competition)

6.4.3 Event Logistics

Team Village

Each team is provided with a 10' x 10' working area in a tent that includes two tables / seven chairs, one electrical outlet (120V 60 Hz 15A), and a wireless internet connection. The Team Village is a tent with sidewalls that resides on a blacktop asphalt pavement surface. Although the covered workspace is weather resistant, teams are discouraged from leaving sensitive electronics/equipment exposed in the tent.

Teams should conduct development, maintenance, and repair of their systems in their designated area in Team Village. Batteries may be charged during the day at the Team Village but may not be left charging overnight.

Team Course Operating Areas (Shoreline)

Teams are provided with a designated area near each course where they are able to set up their equipment. This space consists of a tent-covered area with tables, power, and a hard-wired Ethernet connection.

Power

The United States uses a 120V 60Hz 15A electrical outlet plug. Usually three pins, two parallel blades (one wider than the other), and an offset semi-round pin. The wider blade is Neutral, the shorter blade is Hot/Line and the third pin is Ground. Teams will only get one 15A service and should not connect more load than that.



US electrical outlets

Open to the Public

This event is open to the public. Consider the possible attendance from future employers or sponsors.

6.5 Team Communications

6.5.1 Pre-Competition Communications

RoboSub teams have a variety of opportunities to interact with each other and the RoboSub staff leading up to the event.

TeamTime Meetings

Leading up to the on-site competition, teams are asked to send a representative to regularly scheduled virtual meetings. These TeamTime meetings are hosted by the RoboSub organizers and technical team to provide teams with competition updates and the opportunity to ask questions. Teams can find the meeting dates and details on the [website ↗](#), [Discord ↗](#), and email.

RoboSub Discord

All questions, comments, and suggestions should be posted on the [RoboSub Discord ↗](#). Teams are encouraged to actively participate in the online community and monitor it for the latest news and updates regarding all things RoboSub.

6.5.2 Event Communications

Team Lead

Each team must designate a student team member as their team lead. The team lead is the only person allowed to speak for the team. The team lead is the only person permitted to request vehicle deployment, run start, run end, or vehicle retrieval. The team lead must be conversationally fluent in English to communicate with RoboSub staff. Teams who do not have members fluent in English should contact RoboSub staff as soon as possible.

Technical Director Team

The RoboSub Technical Director Team consists of a Technical Director, Safety Inspectors and Course Managers.

Other RoboSub Staff

The RoboSub Staff are identified with "Staff" shirts.

6.5.3 RoboSub Website

The official competition website is www.RoboSub.org/2026 ↗. This website includes all official documents and a detailed list of the registered RoboSub teams. Helpful resources, past competition results, and other engagement opportunities can be found on this website. Information and documents are updated regularly, and it is the team's responsibility to check the website for updates.

6.6 Data Sharing

A Data Sharing project has been established for registered teams competing in RoboNation's autonomous competitions: [RoboBoat ↗](#), [SUAS ↗](#), [RoboSub ↗](#), and [RobotX ↗](#). This project aims to increase collaboration between teams and to provide access to shared resources and test data to validate and debug the reliability and robustness of teams' machine vision algorithms.

For the data sharing guide and more information on Data Sharing, visit [RoboNation.org/data-sharing](https://robonation.org/data-sharing). ↗

6.6.1 Data Sharing Access Requirements

During the registration process, teams must provide a generic email account and a team acronym that is used in the Data Sharing project. The generic email can be associated with any email provider. An example of the Generic Email is: robosub-team@outlook.com. The team acronym must be within 2-10 characters, abbreviating the team's school or organization. Examples of the team acronym are: RST or RSTEAM.

Only official registered teams maintain access to the Data Sharing project for the competition season. Access is provided to teams at the close of registration, using the generic team email address entered during registration. Contact competitions@robonation.org ✉ for any access questions.

Section 7: Glossary & Acronyms

7.1 Glossary

Phrase	Definition
Semi-Finals & Finals Courses	These courses are designed to allow demonstration of autonomous execution of multiple tasks. They contain an instance of each task.
Team Lead	Designated spokesperson for each team.
Technical Director Team	Technical team that runs the courses, safety inspections, set-up, and tear-down.
RoboSub Staff	RoboSub support personnel.
Judge	Subject Matter Experts that observe and score the Autonomy Challenge and Design Documentation.
Sponsor	Organizations that provide support to RoboSub.

7.2 Acronyms

Acronym	Definition
AUV	Autonomous Underwater Vehicle
N/A	Not available
TBD	To be determined
TD	Technical Director
TDR	Technical Design Report